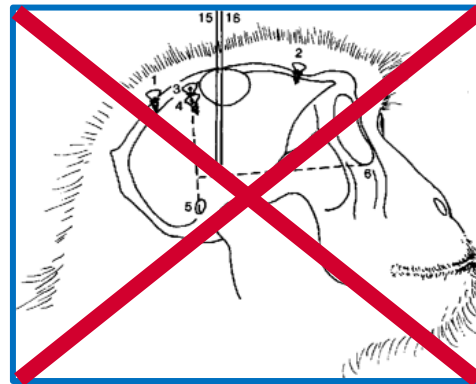
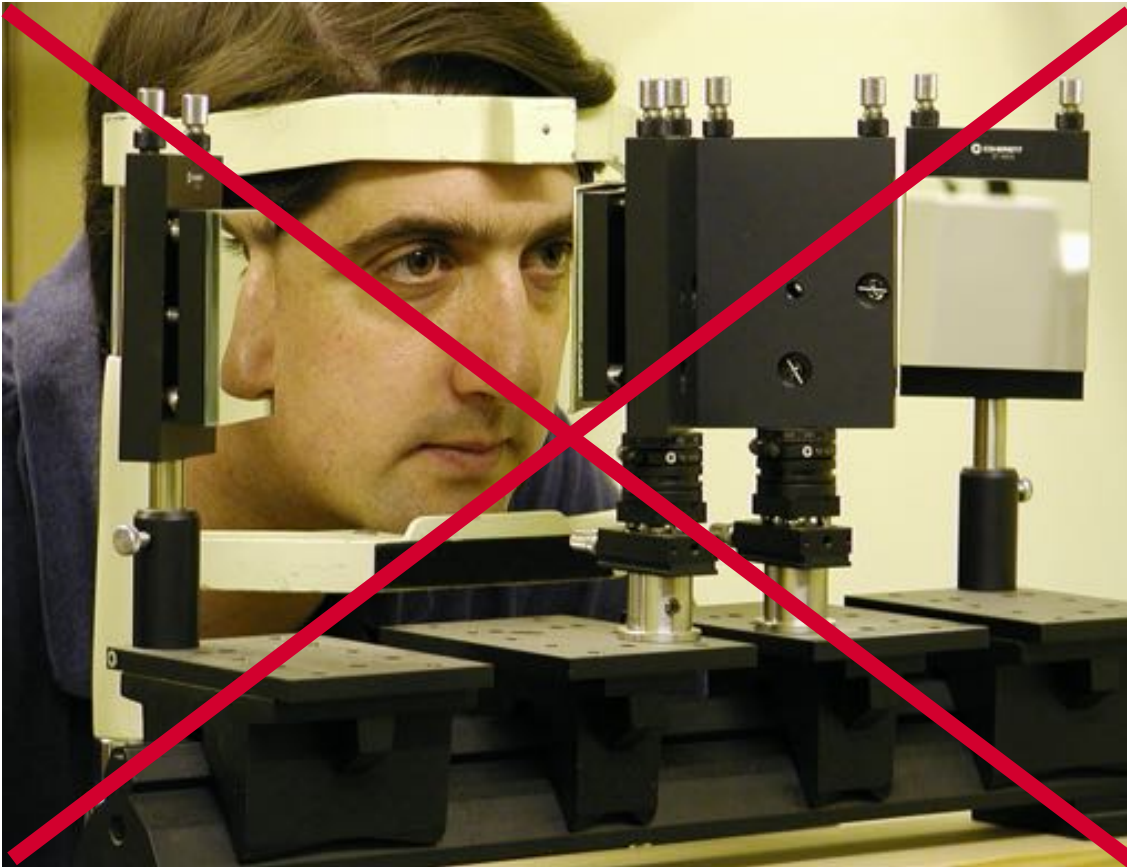


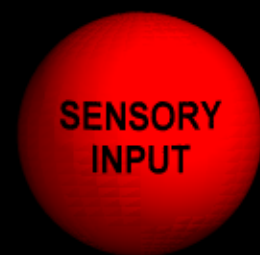
USING VR TO STUDY NAVIGATION AND 3D VISUAL PERCEPTION IN FREELY MOVING OBSERVERS

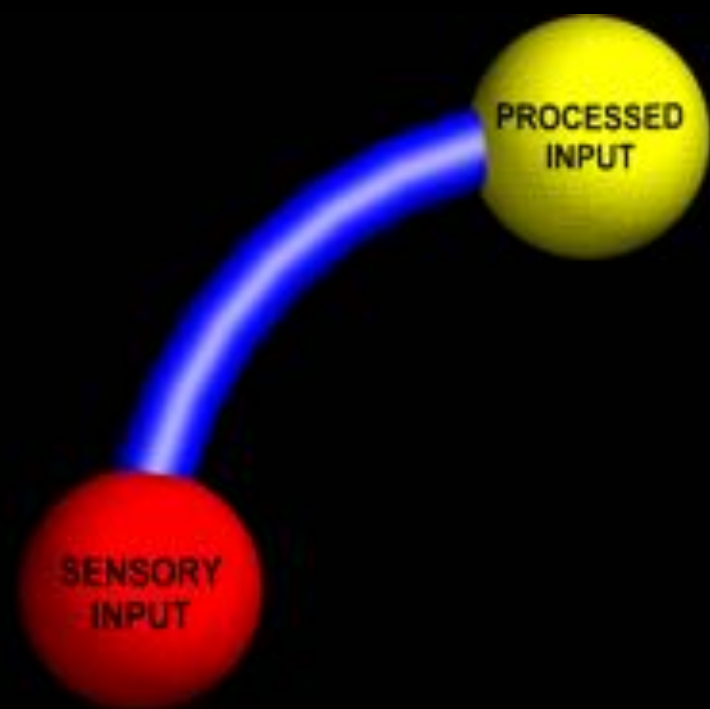


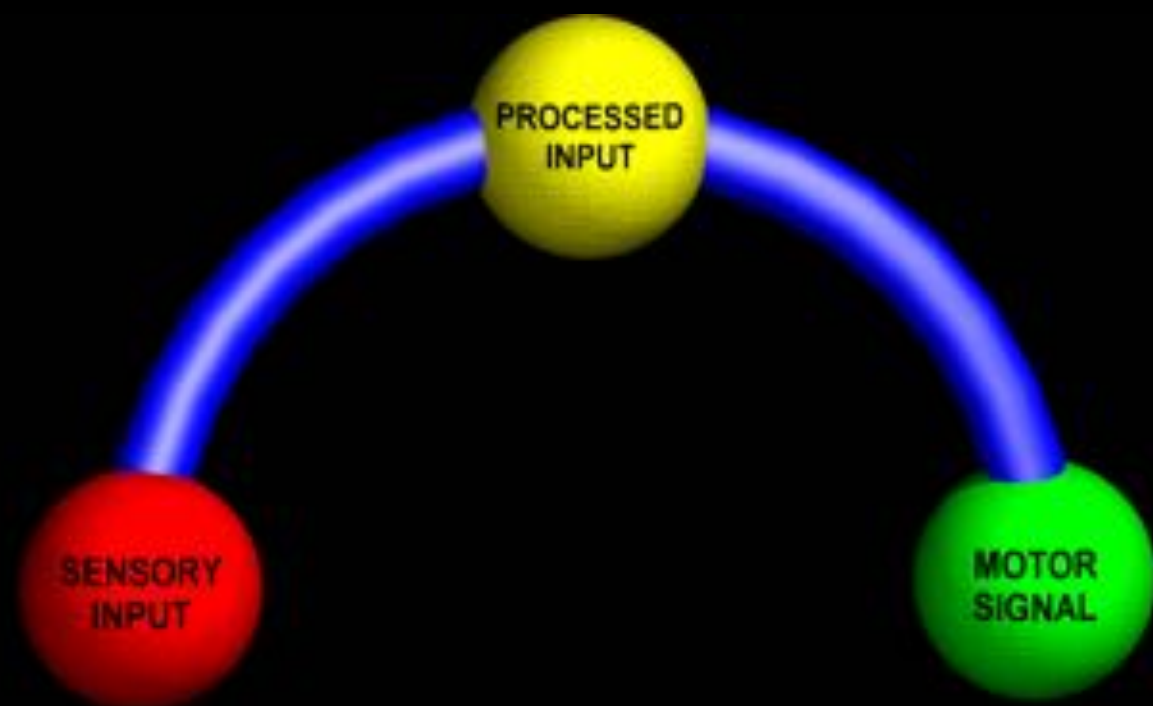
Andrew Glennerster

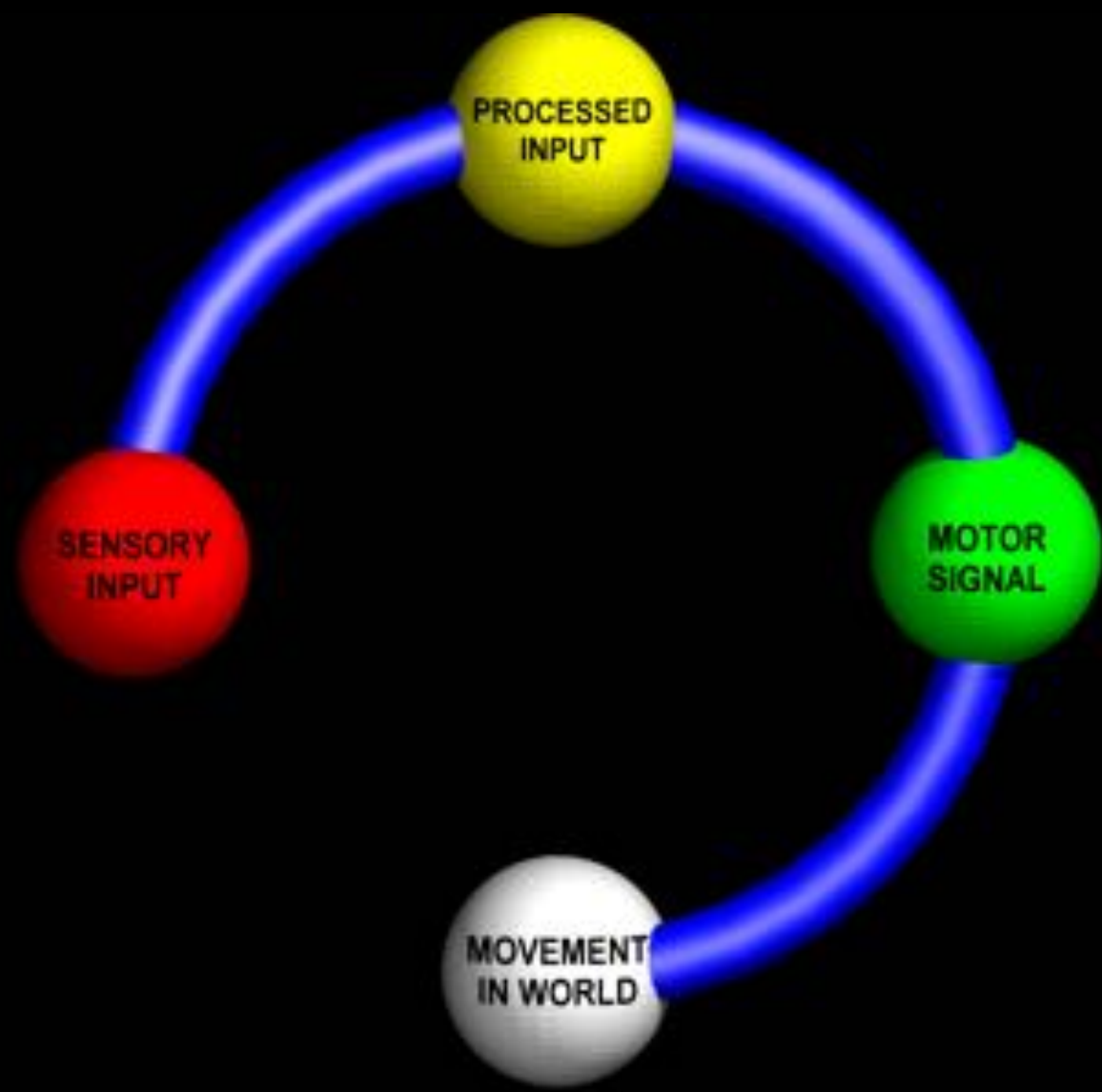
How NOT to do experiments

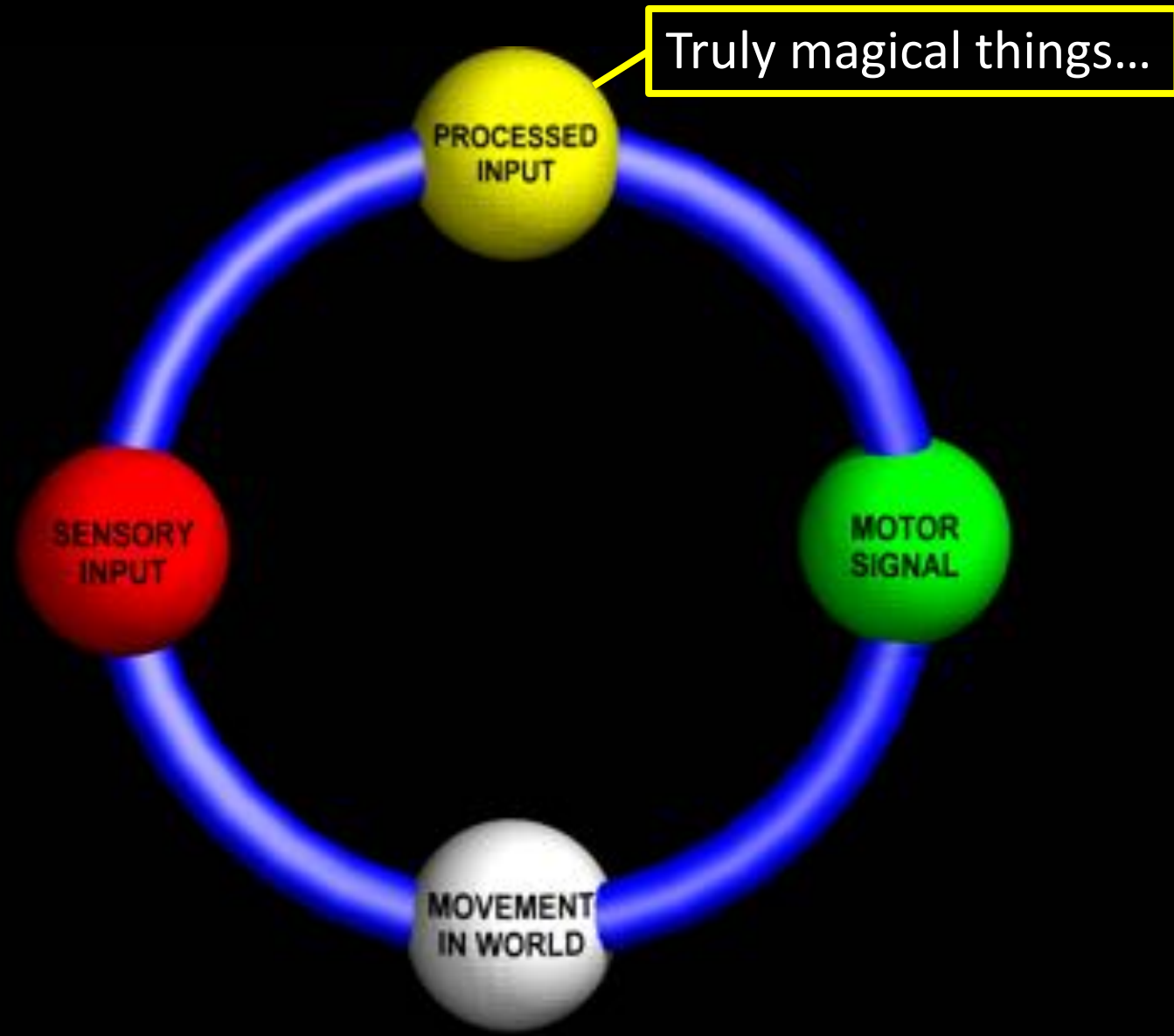




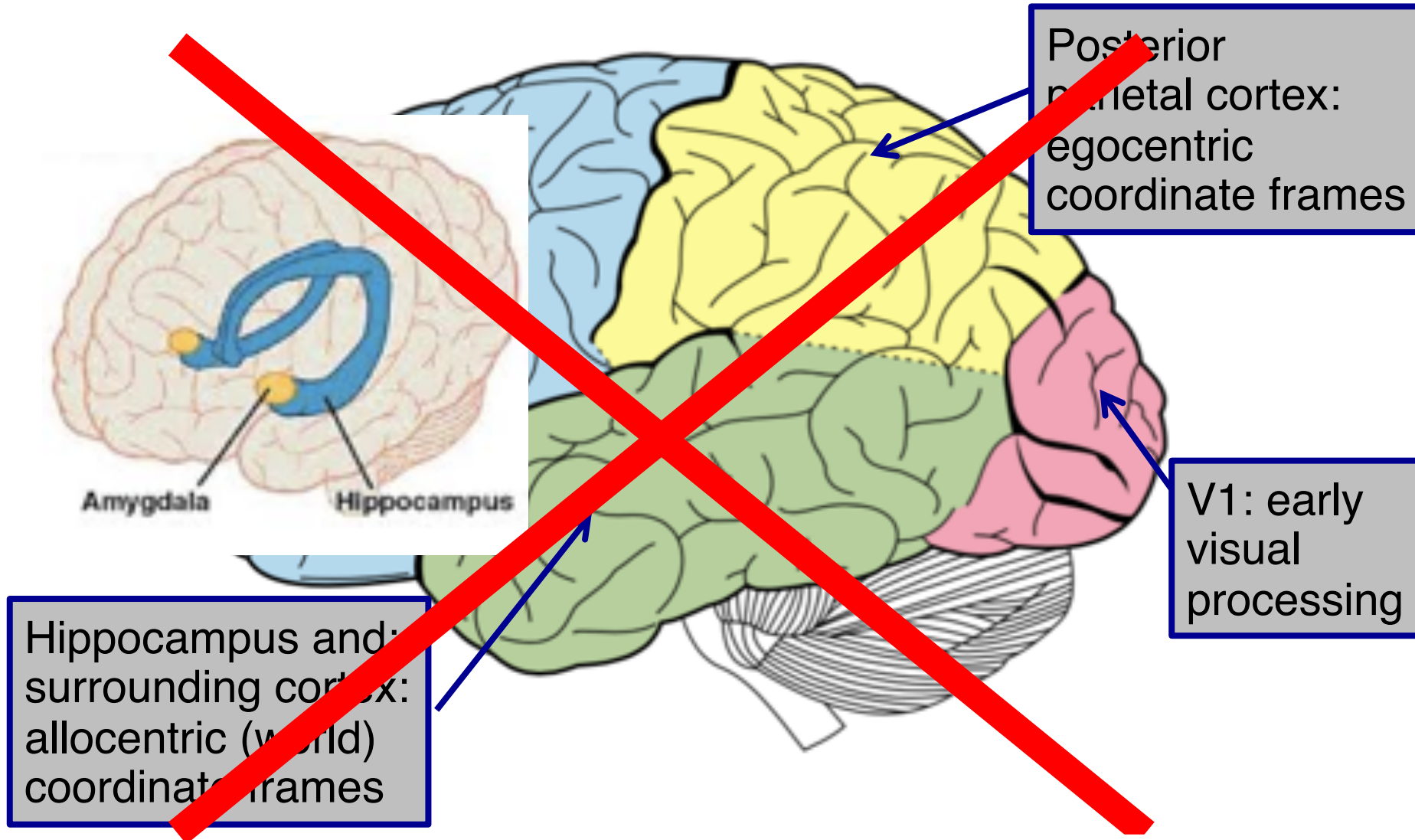


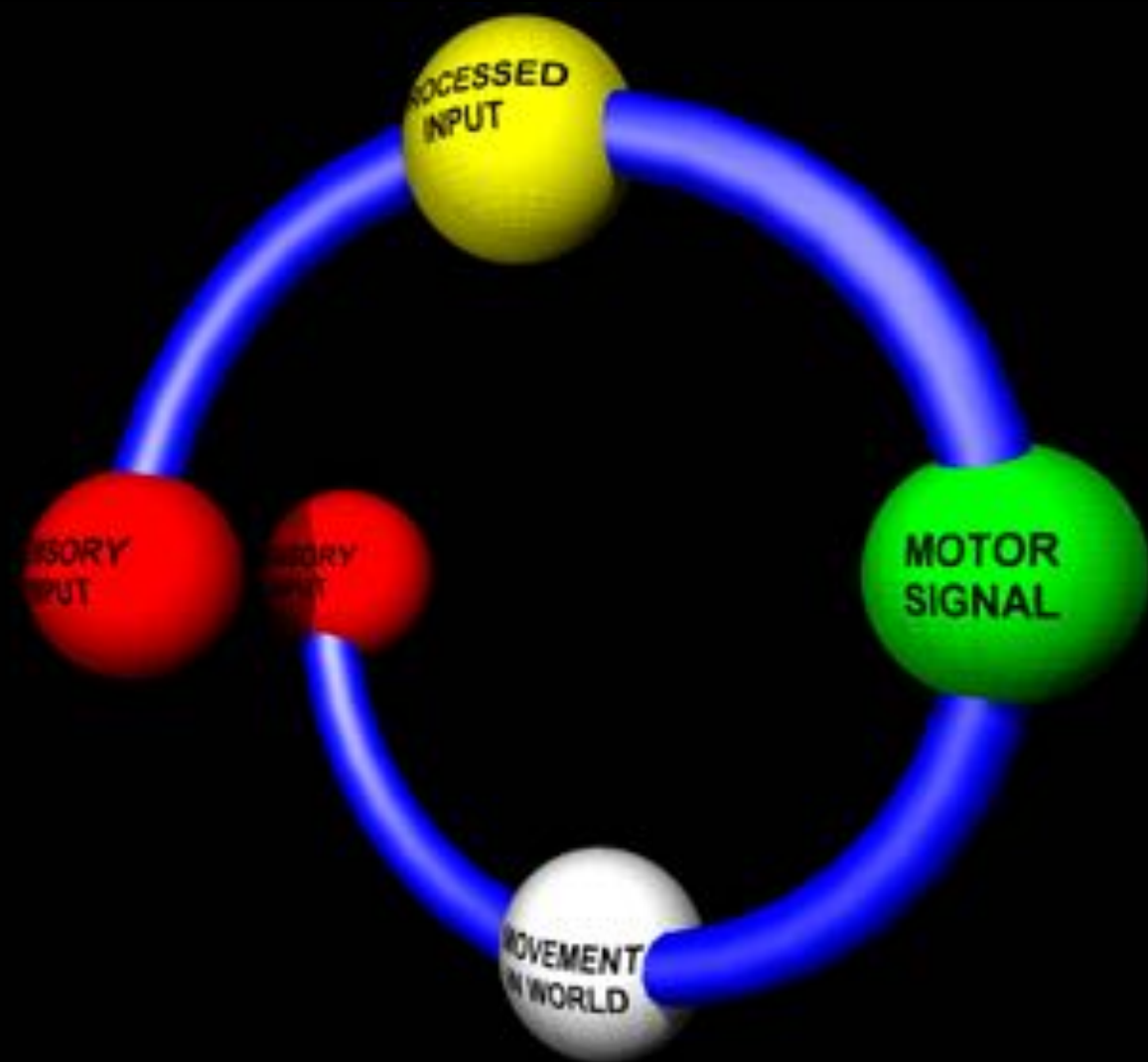


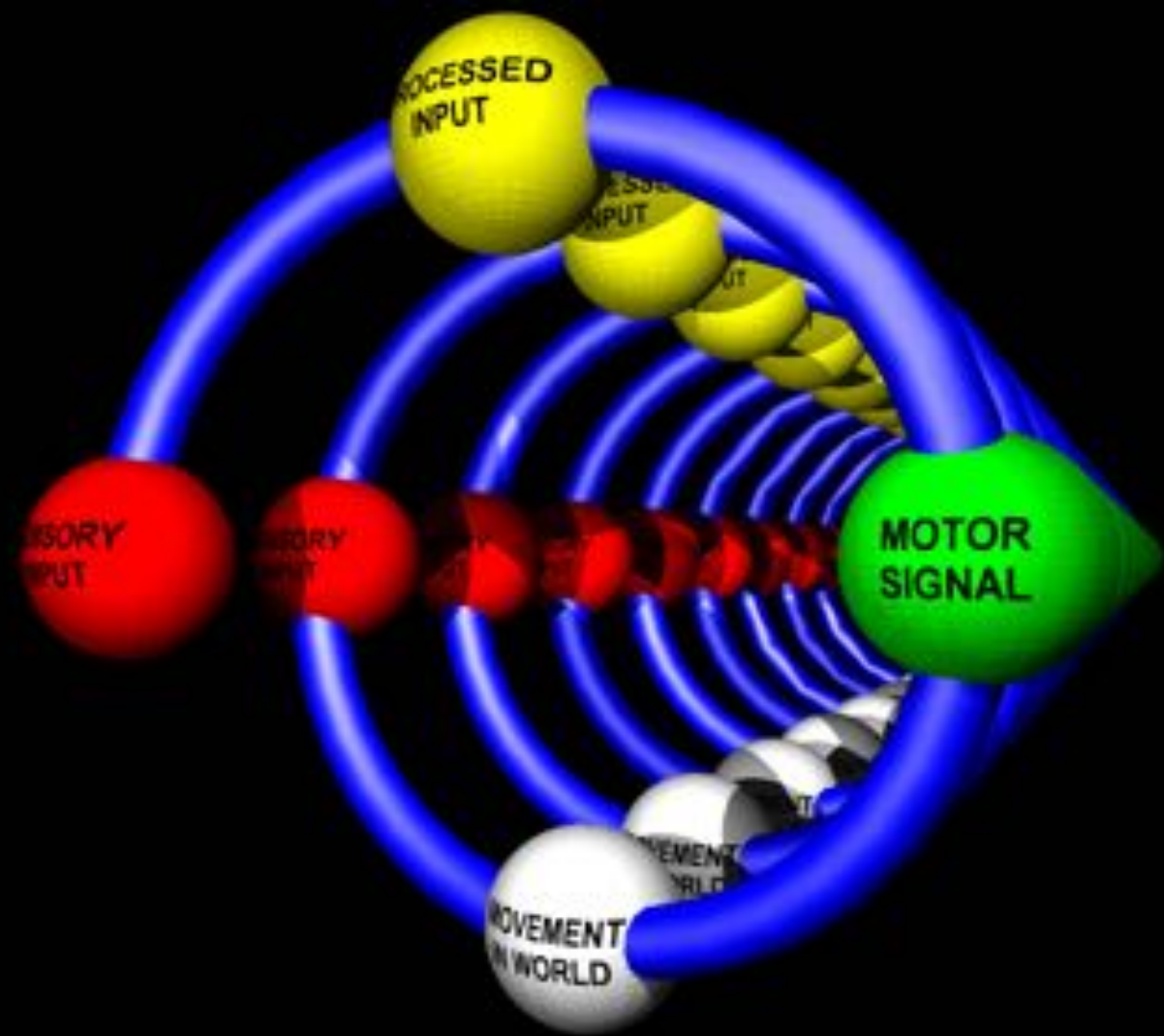


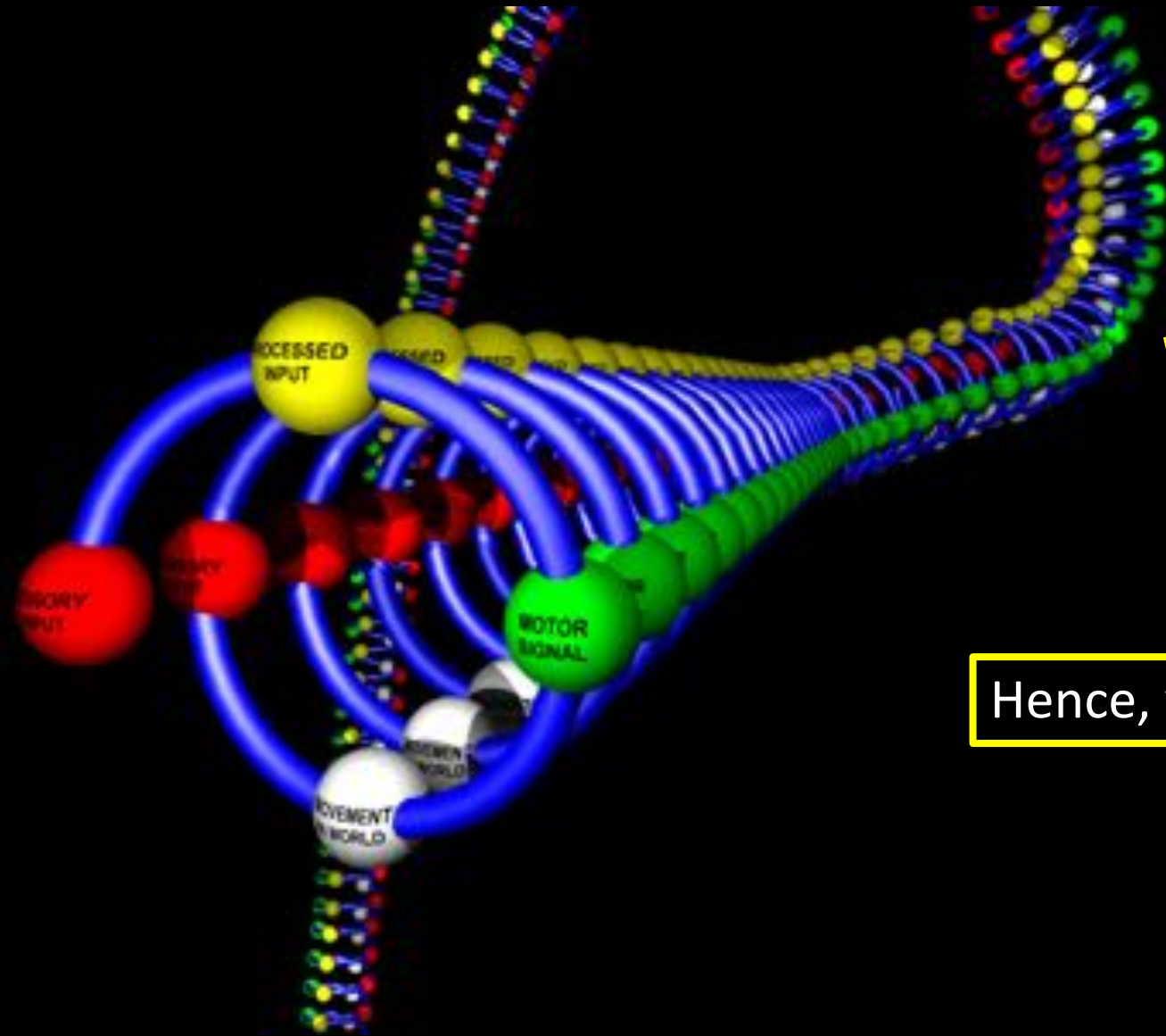


Current hypothesis







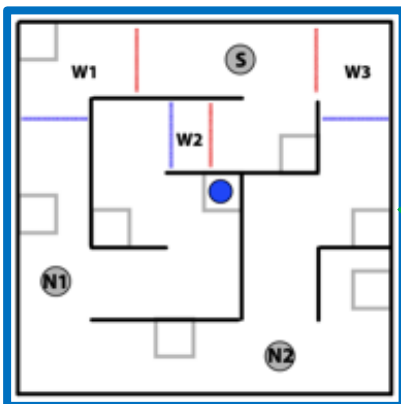


Hence, we need VR...

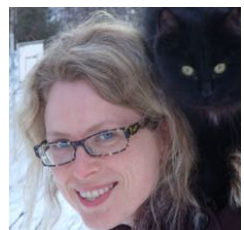
Three experiments:



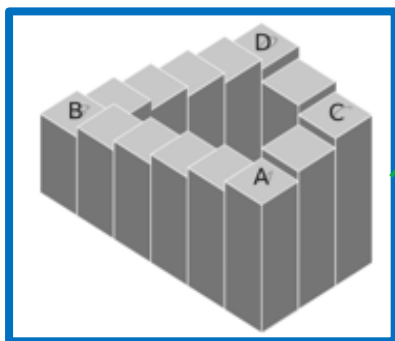
Alex Murry



Jenny Vuong

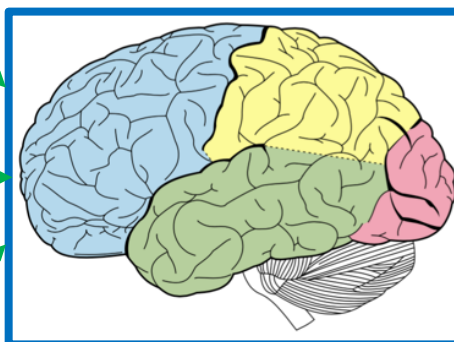


Ellen Svarverud



Are there 3D
representations
in the brain?

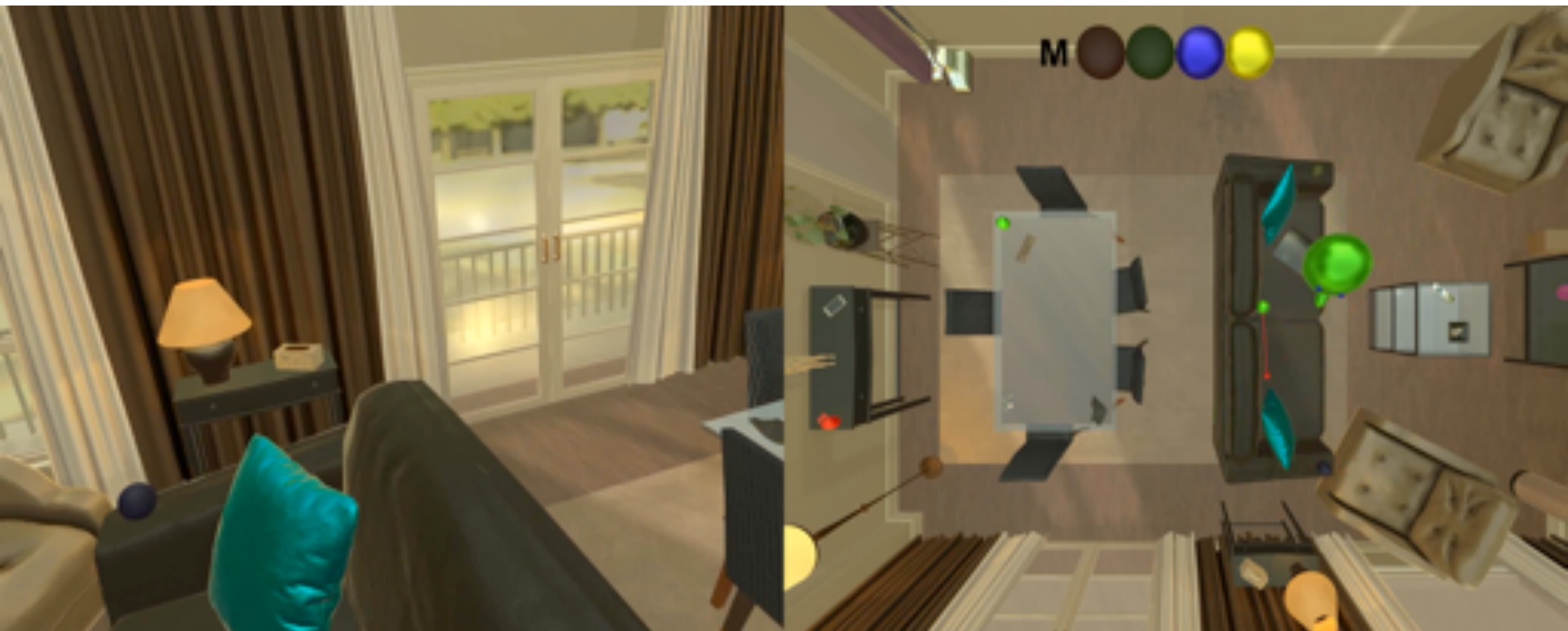
Criterion:
Can a single
3D representation explain
performance across multiple
tasks?



Only possible to test
alternative hypotheses
if the observer moves:
i.e. VR is essential

Others using VR to argue
a similar case:

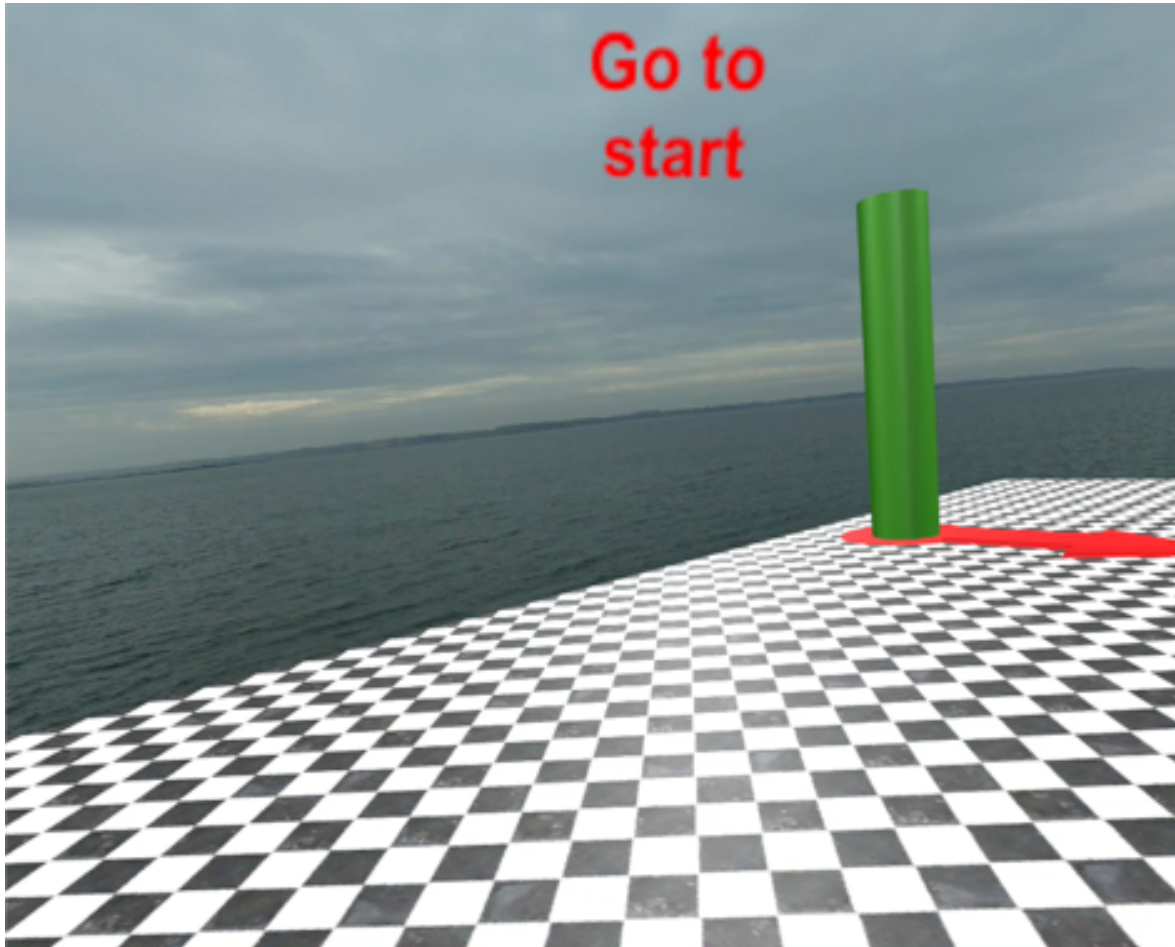
- Warren (2019), *Journal of Experimental Biology*
- Strickrodt, Bühlhoff, Meilinger (2018), *Journal of Experimental Psychology: LMC*
- Gillner and Mallot (1998), *Journal of Cognitive Neuroscience*





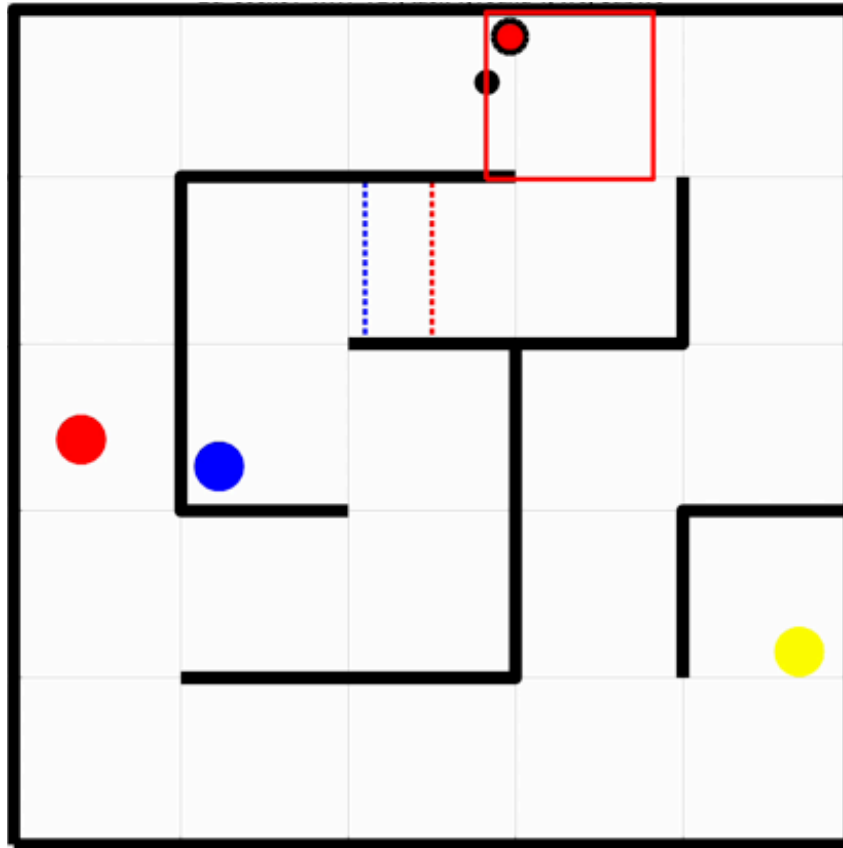
Alex Muryy

Learning to point to targets in a maze



- Tasks:
- (i) find targets in specified order and
 - (ii) point to them...

Learning to point to targets in a maze



Life gets
harder...

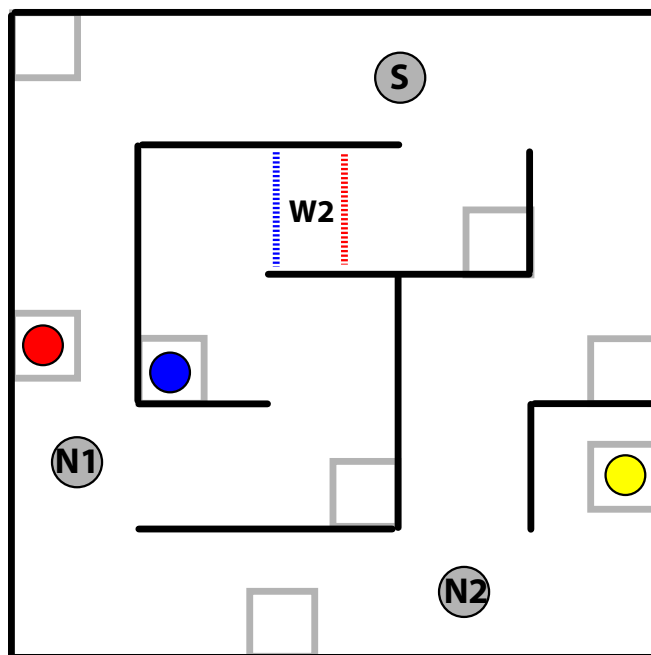
Learning phase (repeat x5):




- a) Navigation: go Start-R-G-B-Y
- b) Pointing: from Y point to S, R, G, B

Test phase (x3):

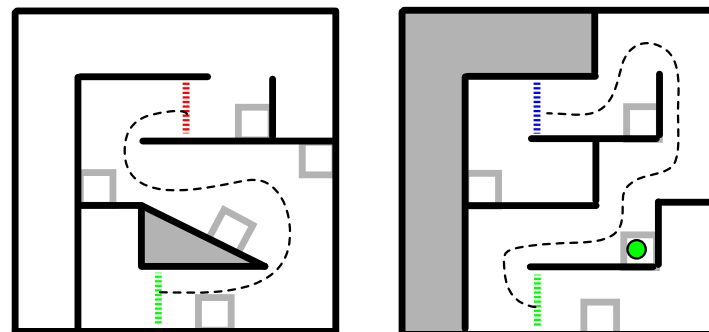
- a) Random sequences
- b) Point to all targets

Non-metric scene: 1 wormhole

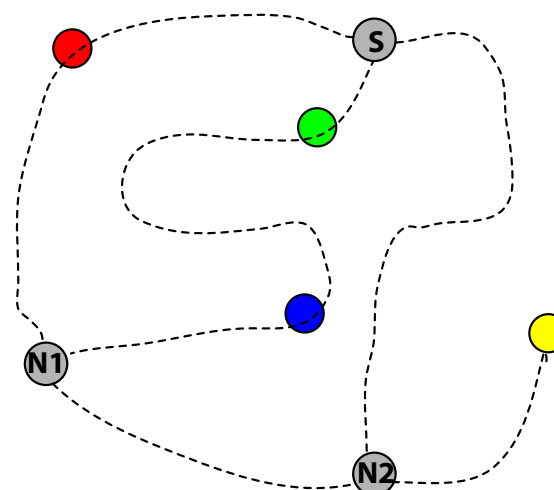


-  - topological node
-  - small walls
-  **w** - wormhole

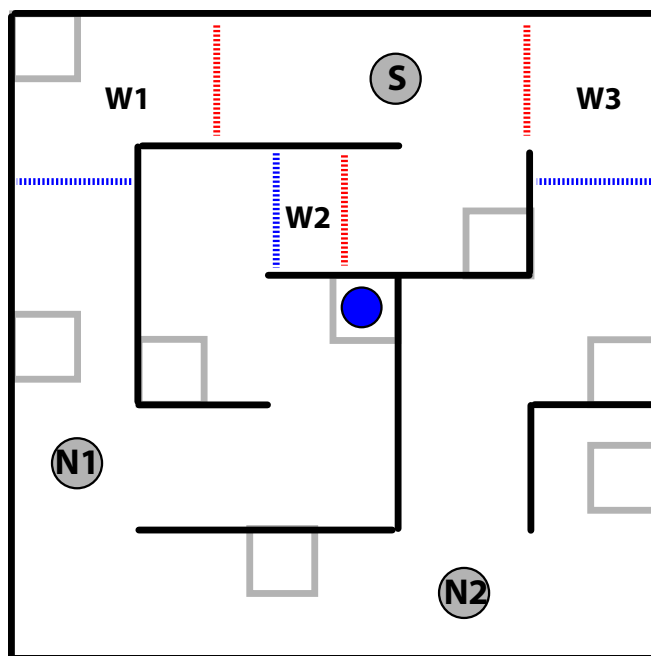
wormhole






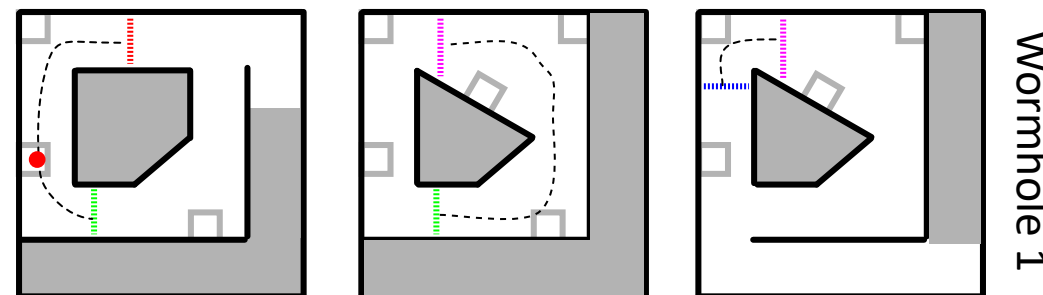
topological graph



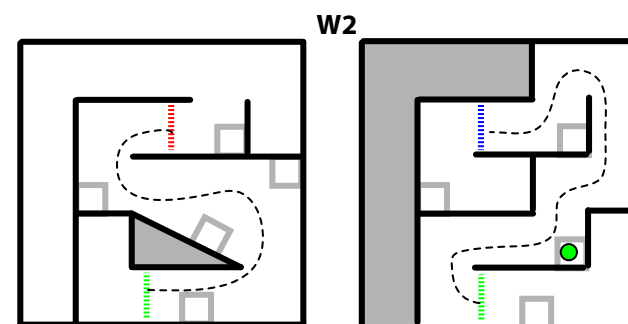
Non-metric scene: 3 wormholes



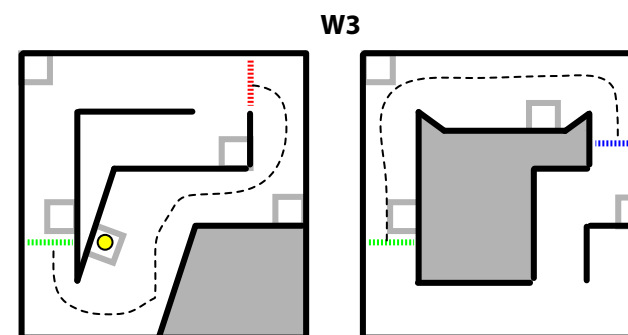
-  - topological node
-  - small walls
-  - wormhole



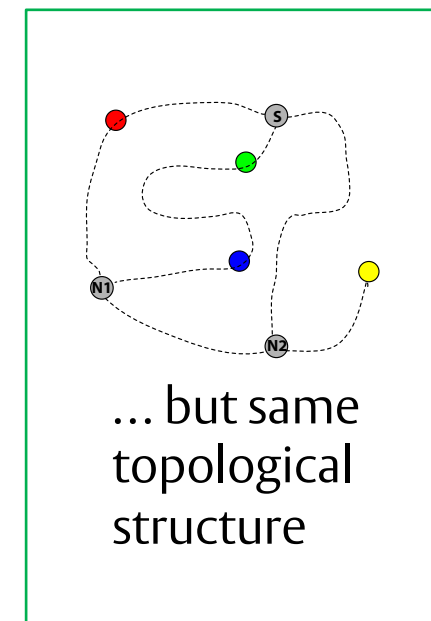
Wormhole 1



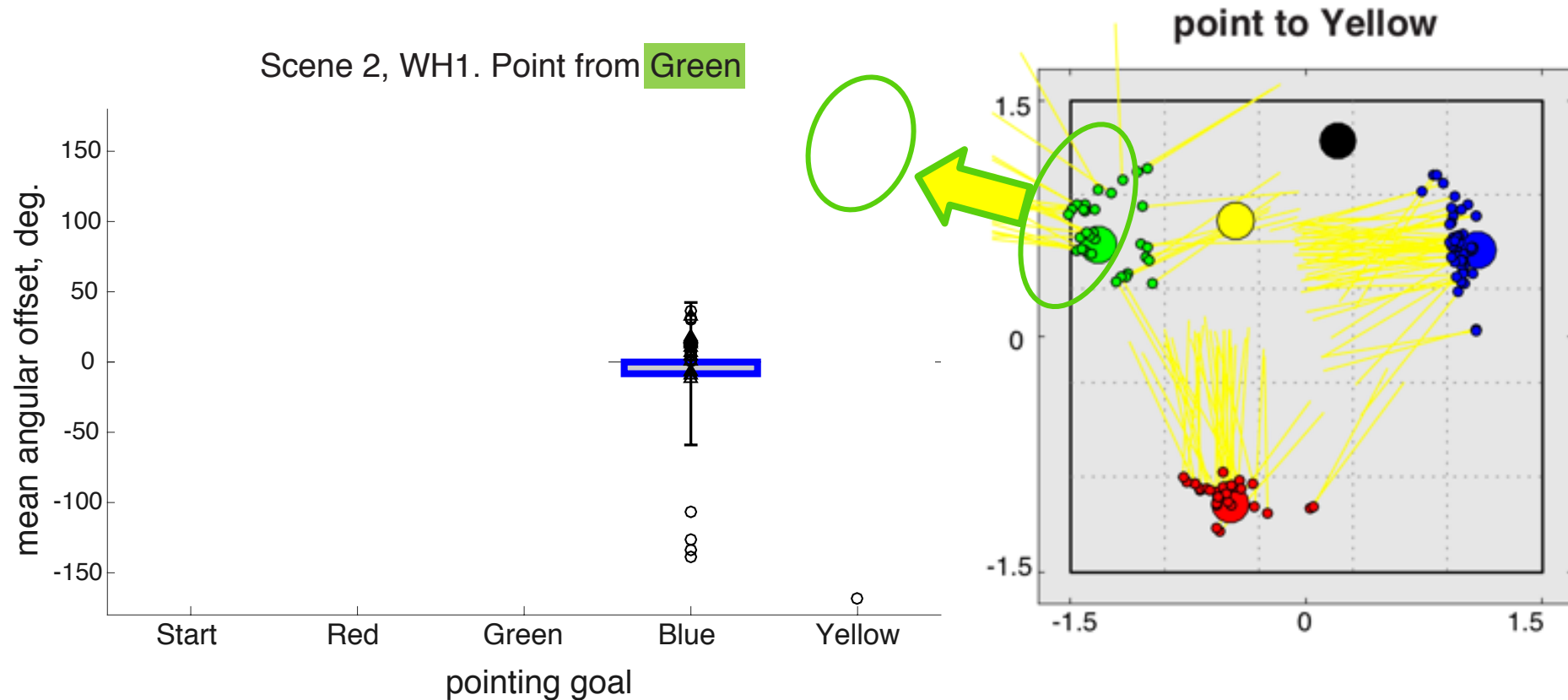
Wormhole 2



Wormhole 3

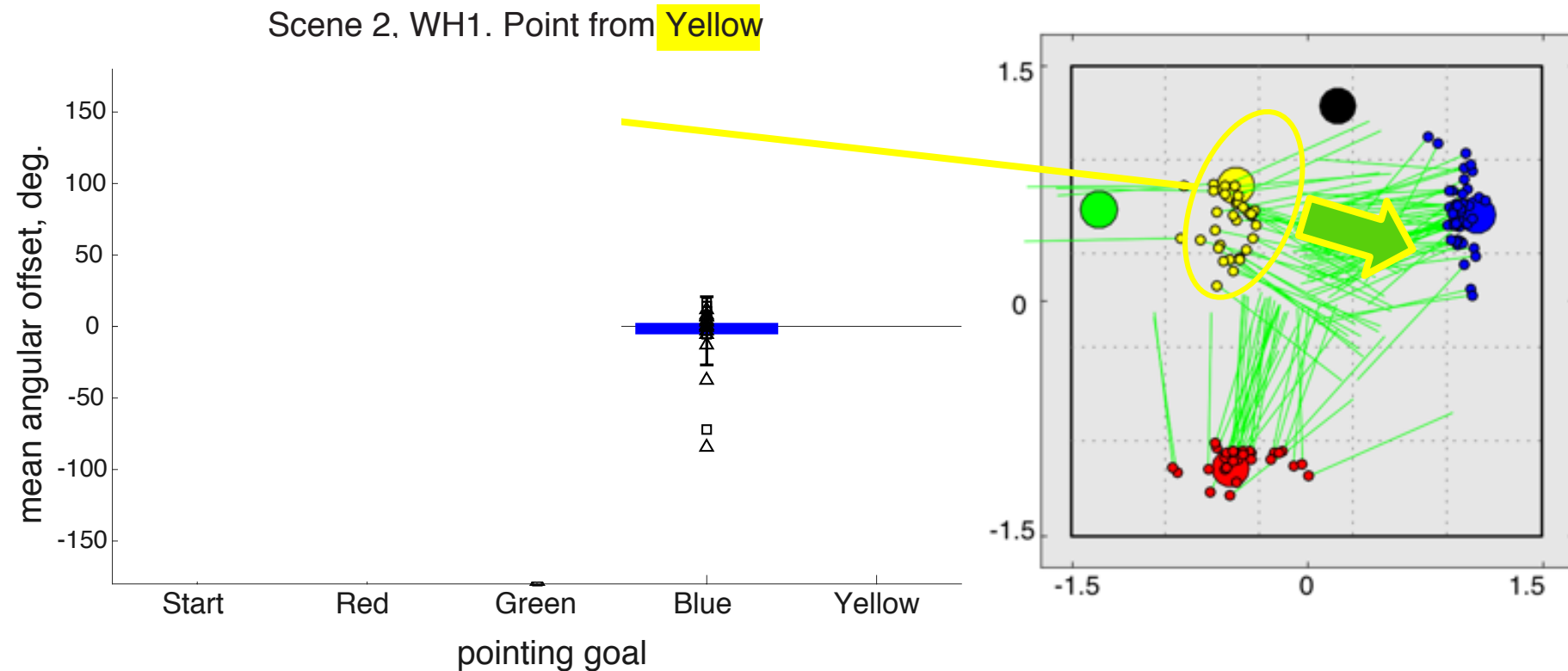


Pointing: very large errors



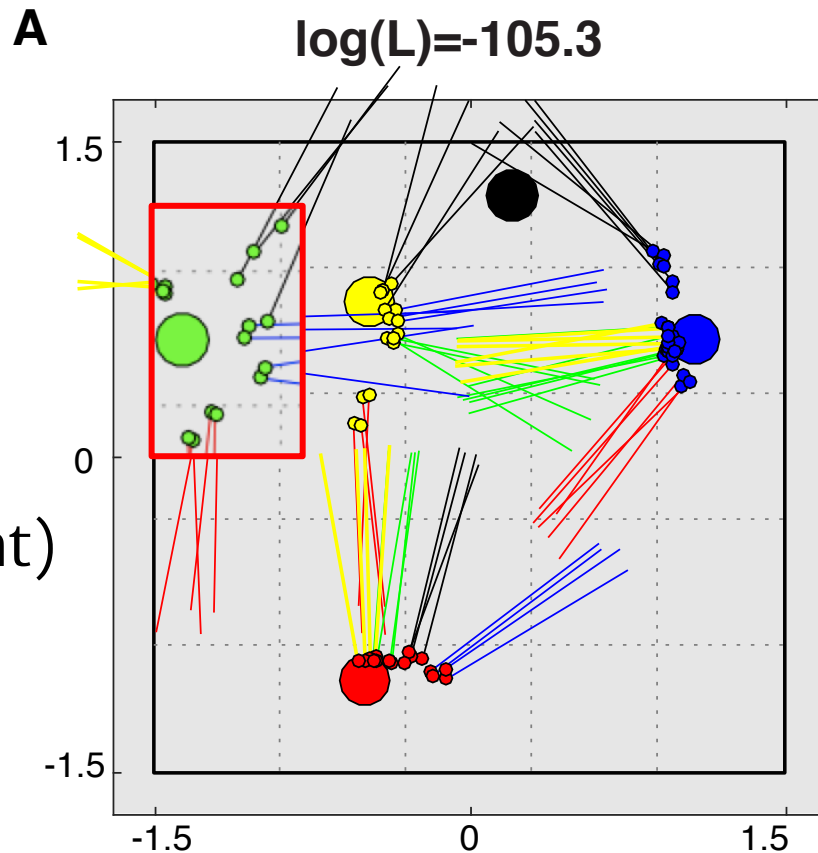
Pointing to some targets leads to very large, systematic errors.

Pointing: very large errors



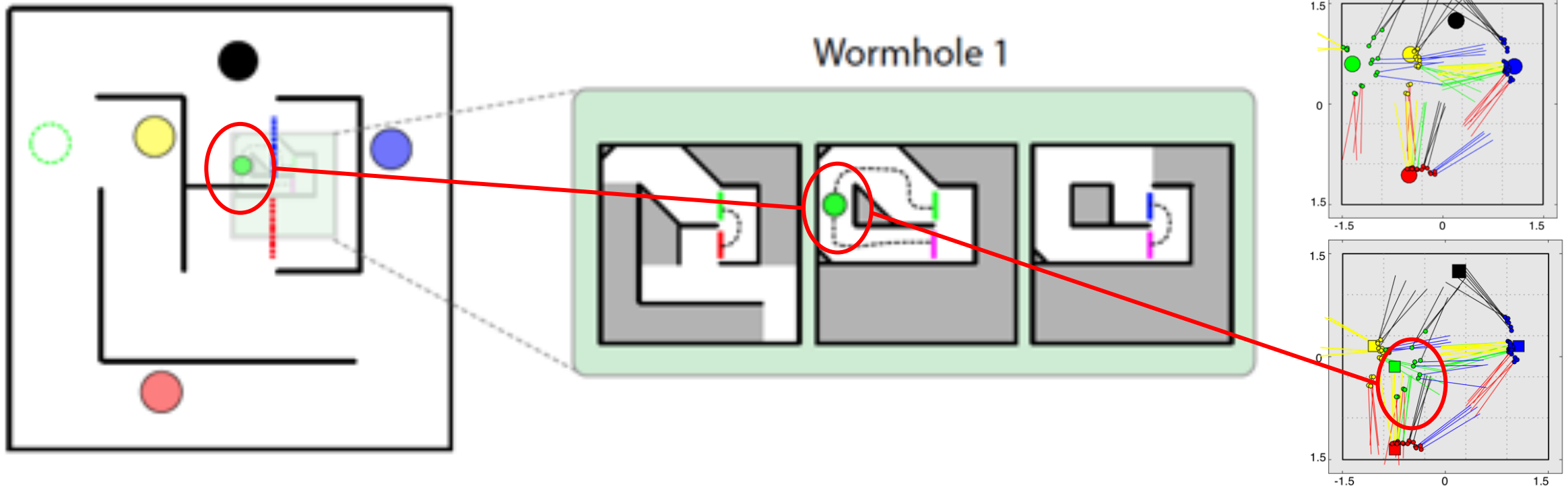
Pointing to some targets leads to very large, systematic errors.

Pointing: very large errors



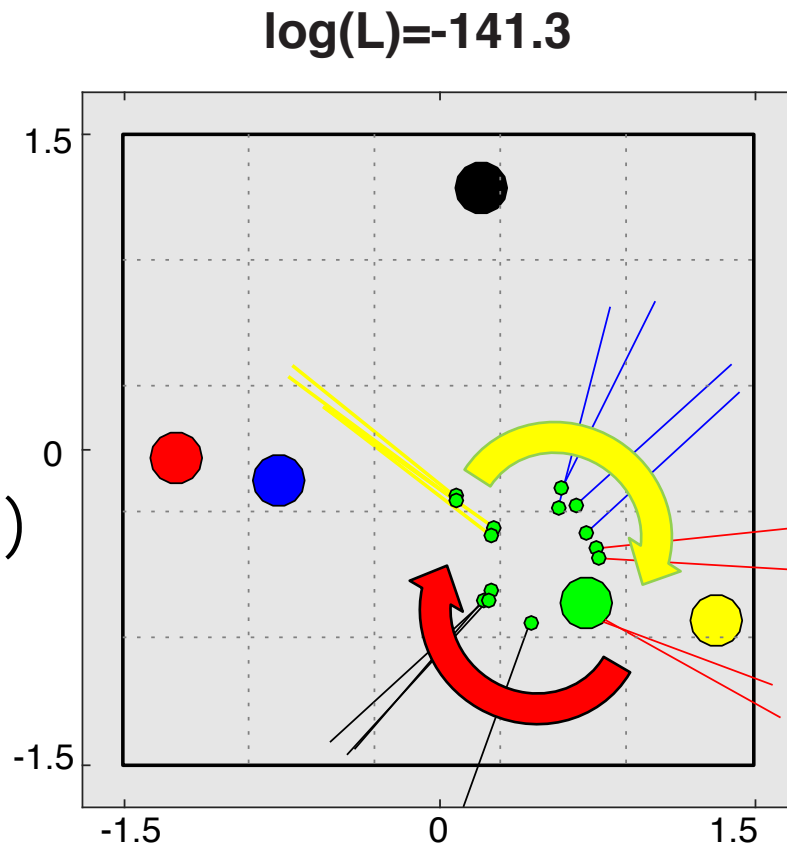
In the most likely configurations, green is to the east of yellow.

Pointing: very large errors



It seems as if participants 'squash' the wormhole corridors into a smaller region than they actually occupy .

Adding in rotation



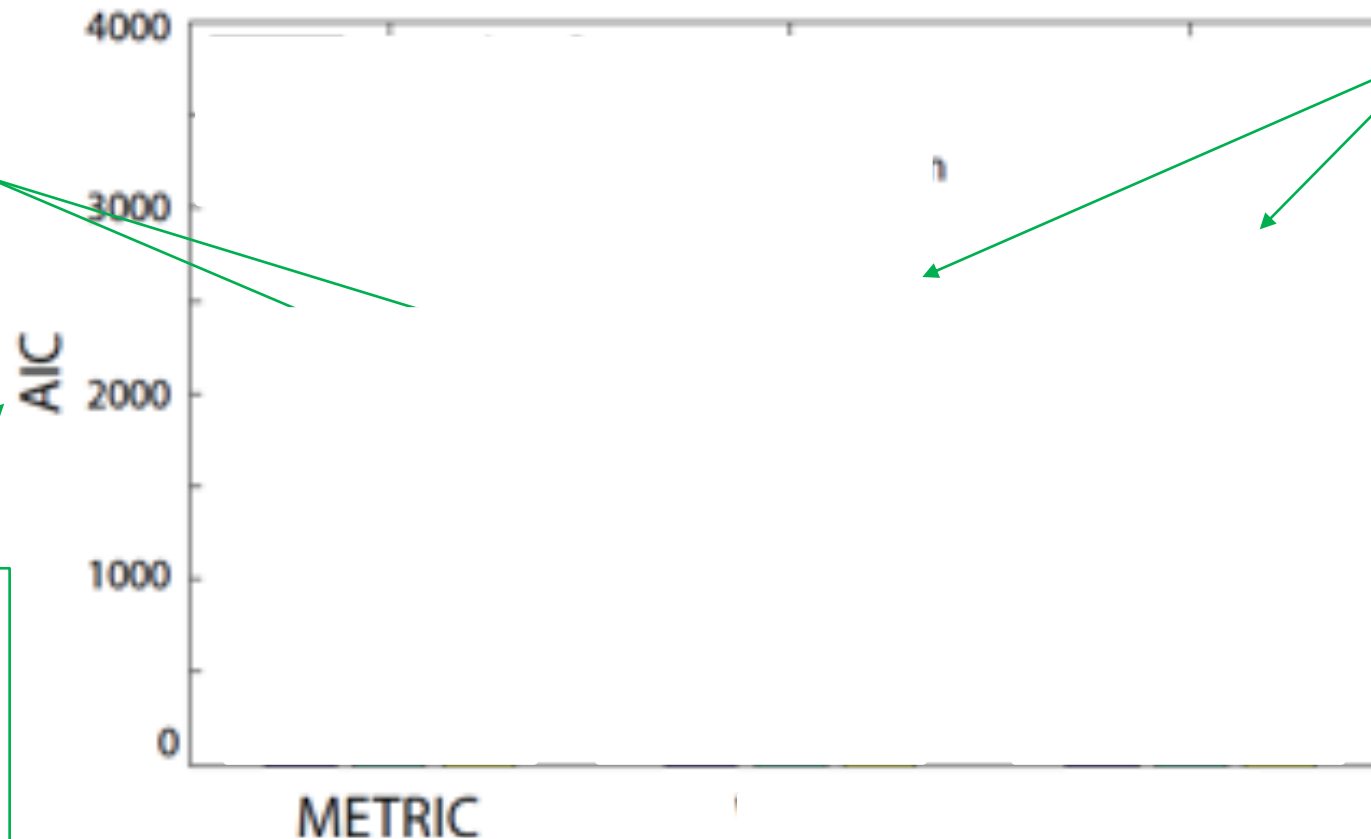
180° rotation
of all pointing
directions

This takes into account the possibility that people are disoriented.
But it is not compatible with a single, consistent 3D representation.

Model comparison

In the METRIC condition, optimised translation and rotation are not better models than the original configuration (when penalized for the extra parameters in the models)

Akaike information criterion, a measure of likelihood (low is more likely)



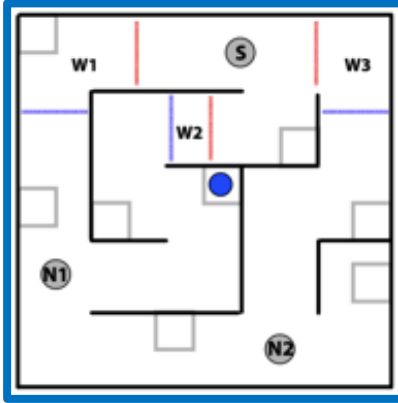
In the WORMHOLE conditions, the best model is one that optimizes the location of the targets (i.e. a distorted world) *and* optimizes the rotation of the observer independently at each pointing zone

This is not a consistent, metric, 3D representation

Three experiments:



Alex Murry



Are there 3D
representations
in the brain?

Criterion:
Can a single
3D representation explain
performance across multiple
tasks?

No

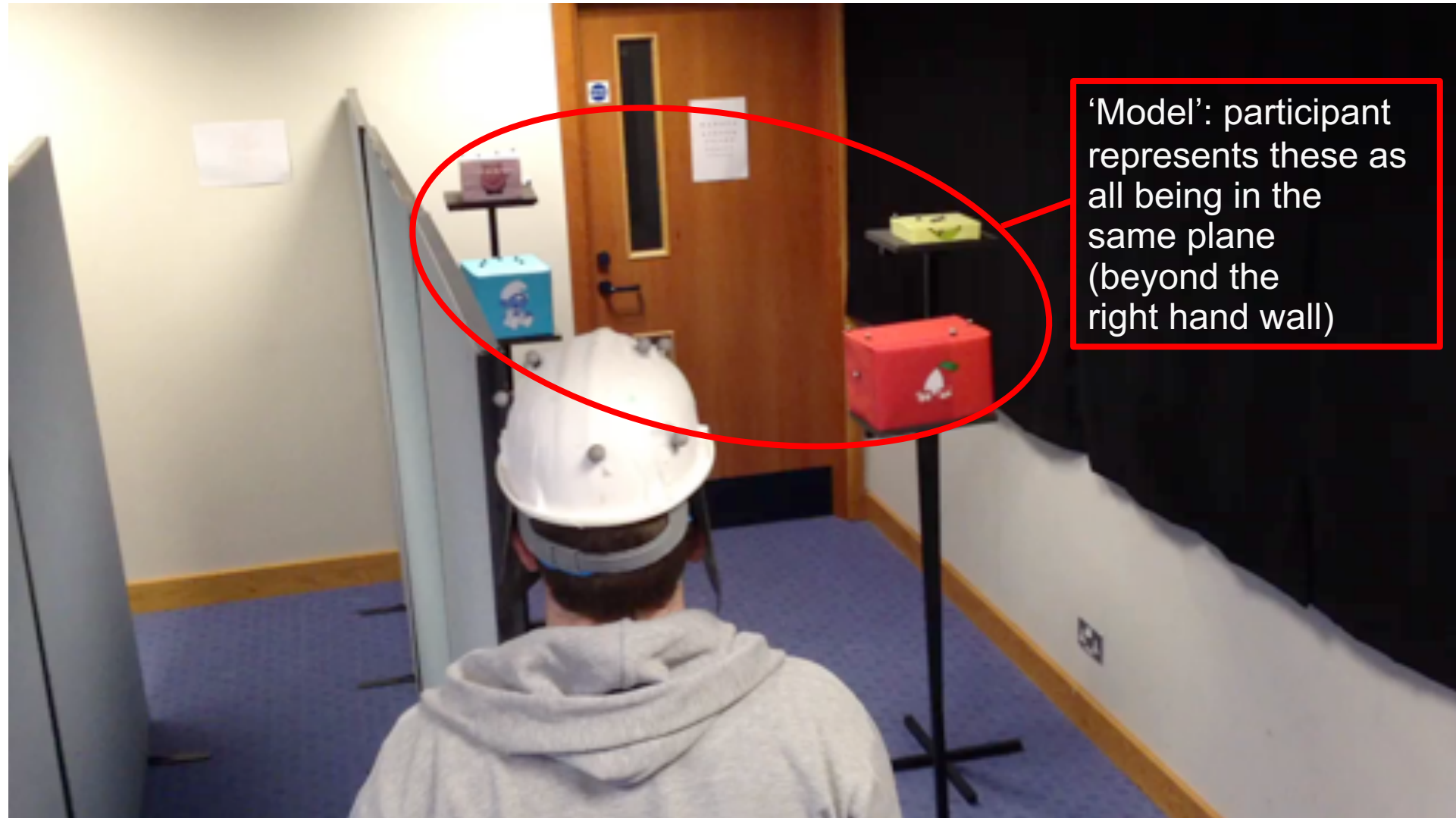
Can we update the visual direction of unseen objects as we move?



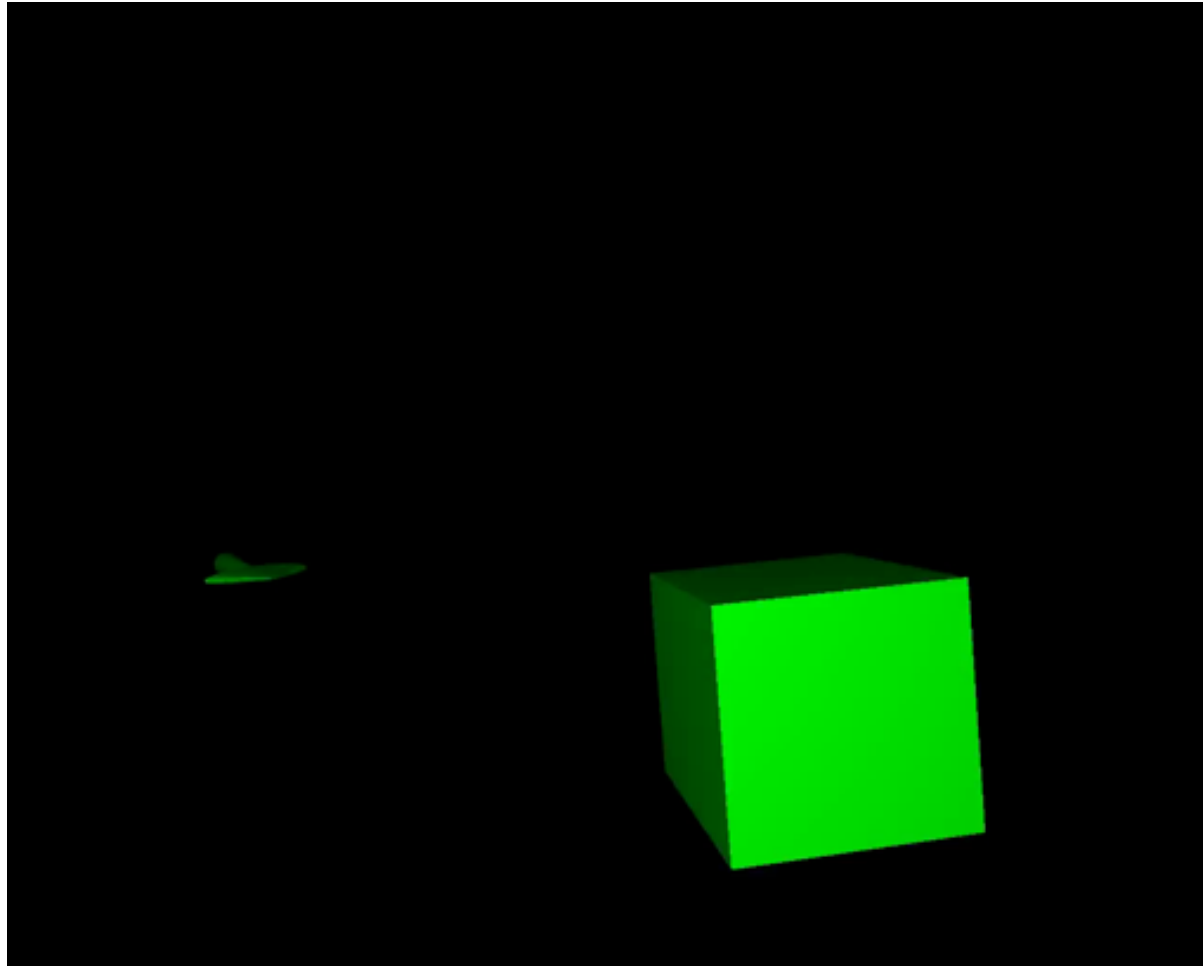
Jenny Vuong



Can we update the visual direction of unseen objects as we move?



Can we update the visual direction of unseen objects as we move?

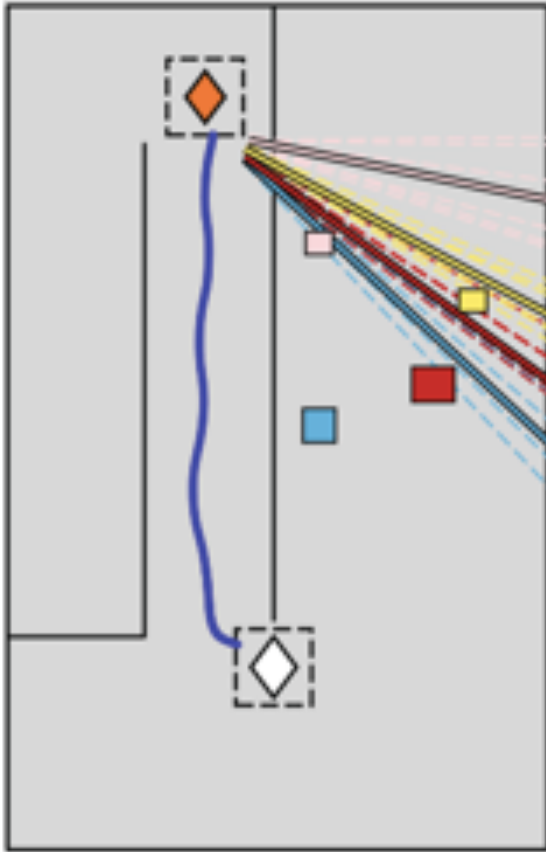


Vuong et al
(2019)
*Scientific
Reports*



nVis SX111 HMD
Vicon tracking

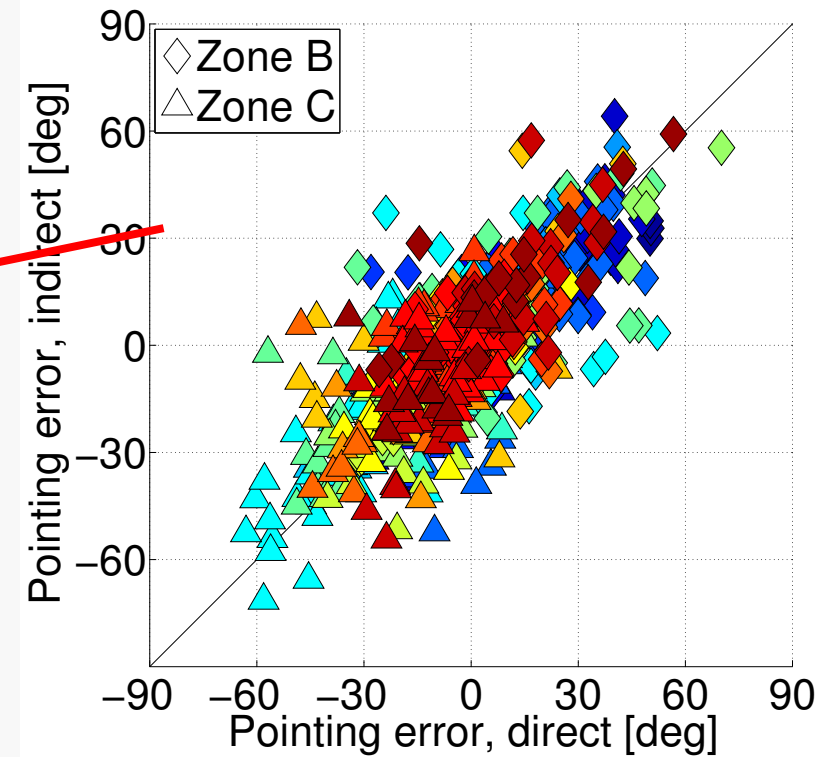
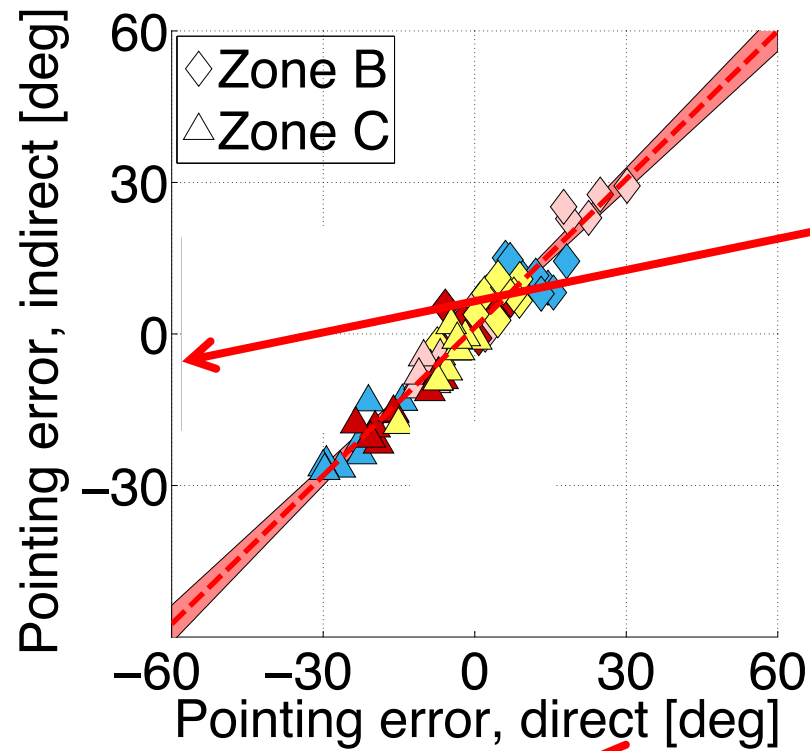
People show large, consistent biases



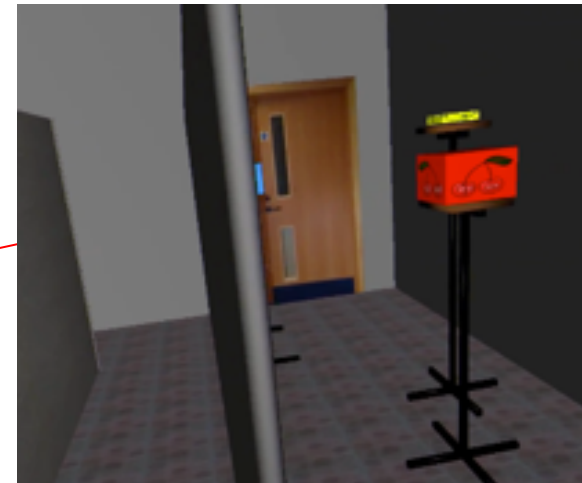
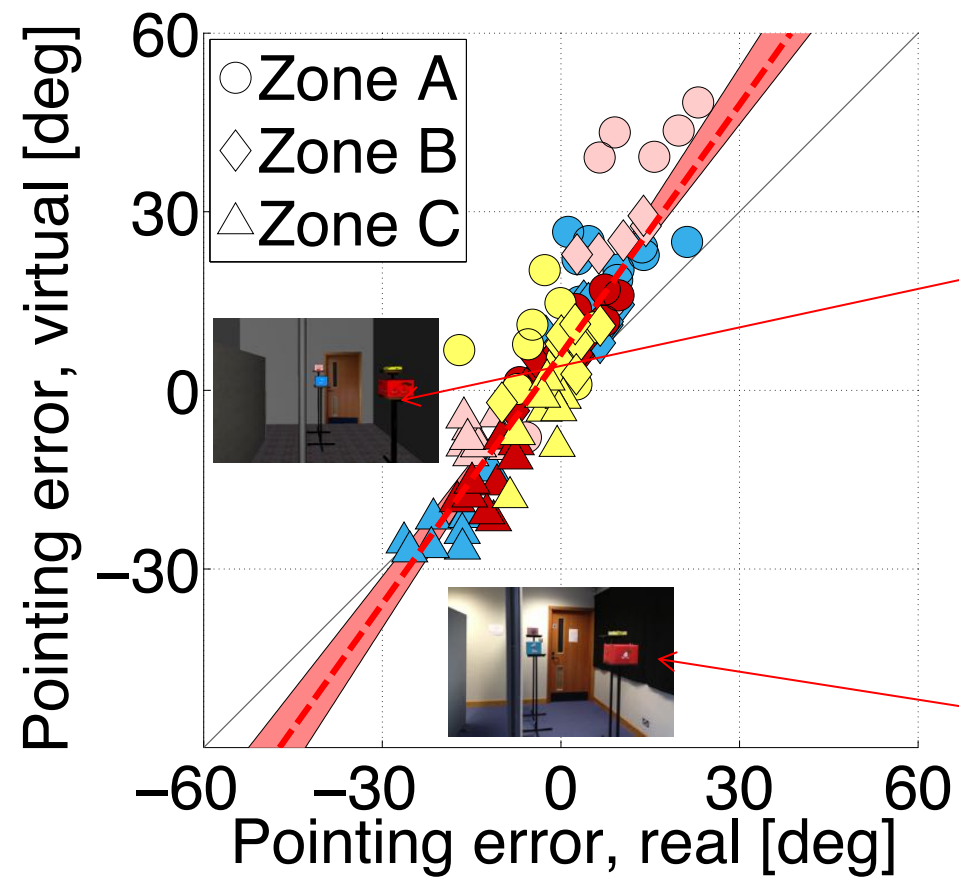
Task:

- view a scene
- walk without any further view of the objects
- point to the objects
- easy to do if we update our location in a 3D reconstruction

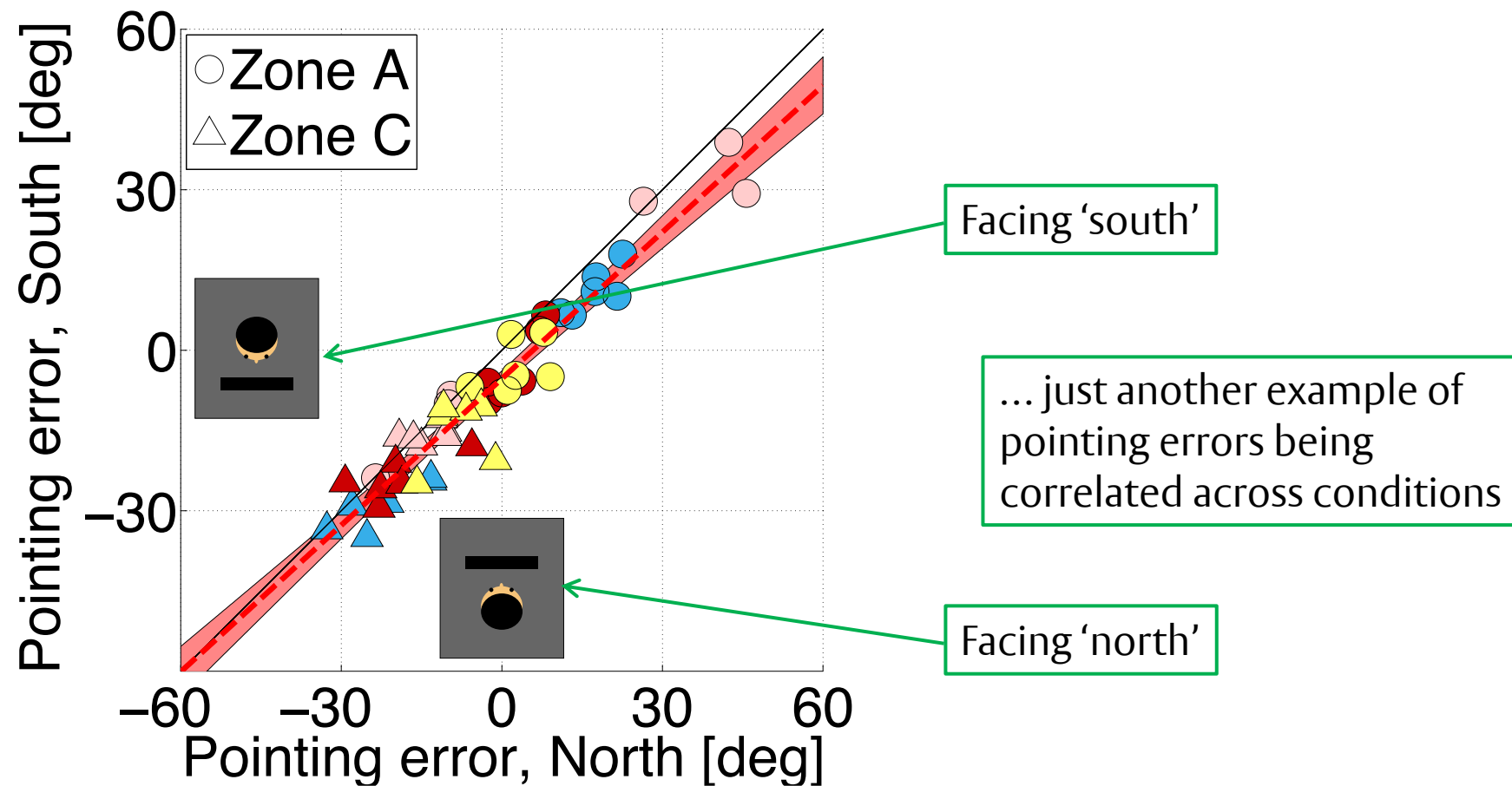
... independent of the route they take ...



... similar biases in real and virtual worlds ...



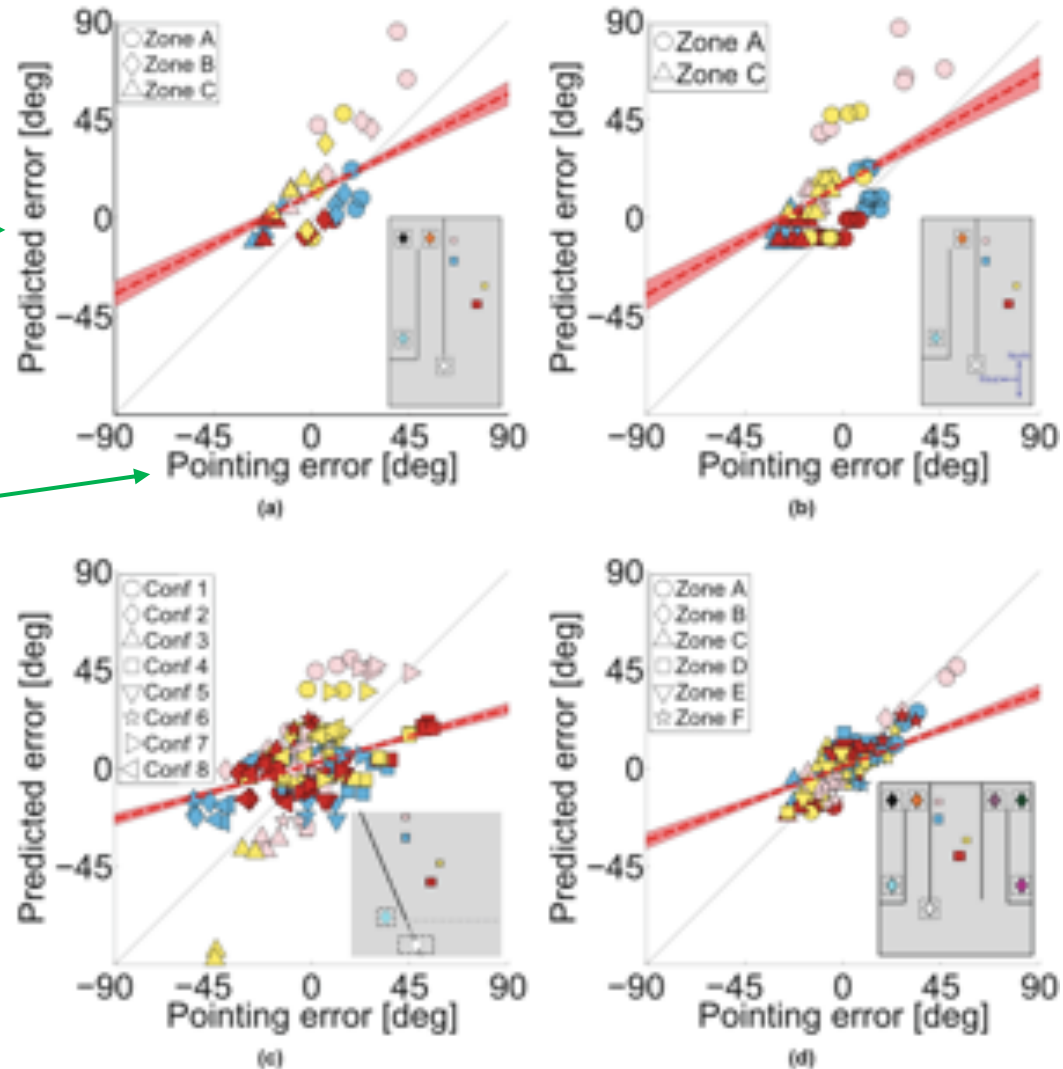
... whether looking 'north' or 'south' ...



If you assume the brain builds a 3D model...

Prediction

Data

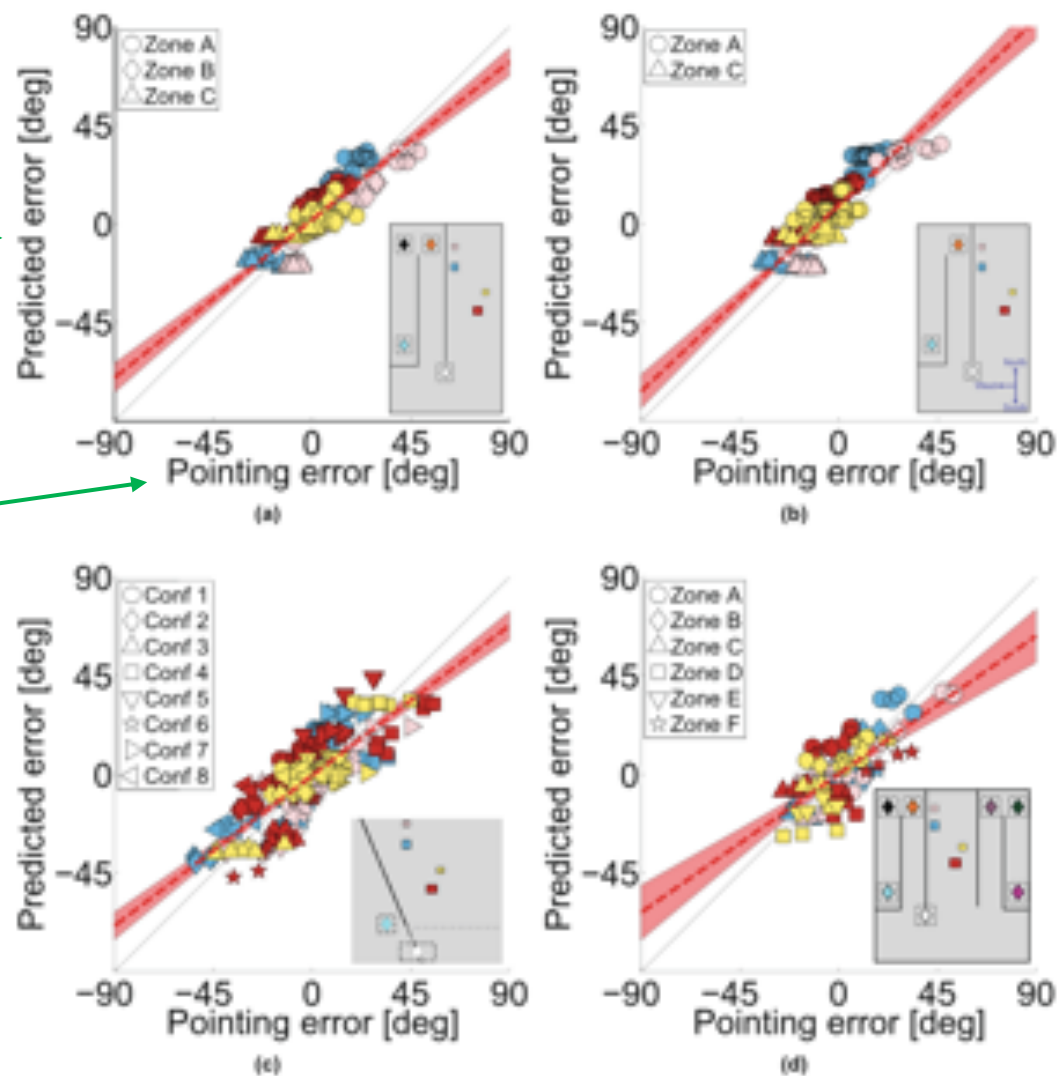


This model is being as generous as possible to the idea that the brain builds a 3D model (either correct or distorted)

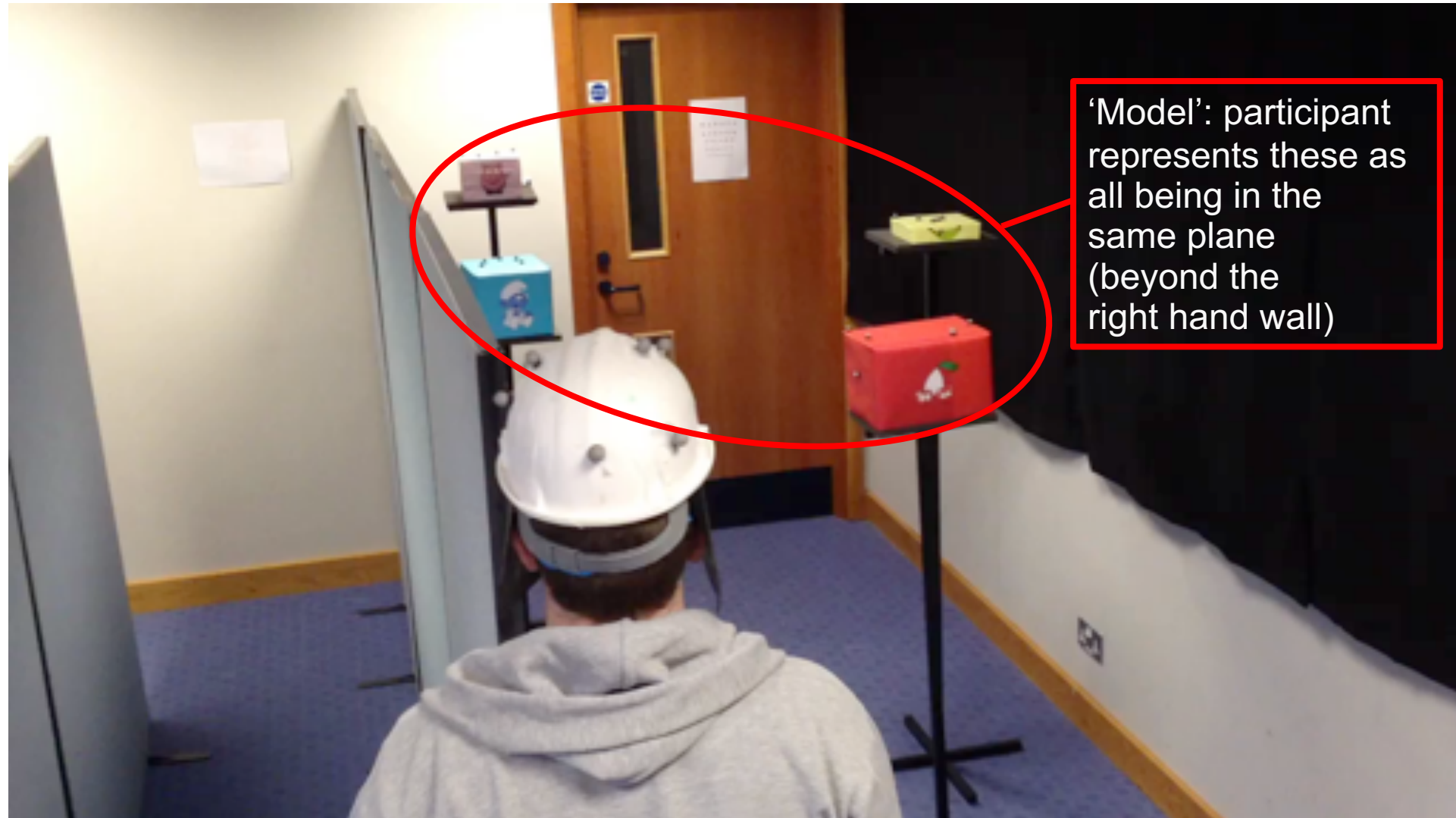
If you assume it does NOT build a 3D model...

Prediction

Data



Can we update the visual direction of
unseen objects as we move?



Three experiments:



Alex Murry



Jenny Vuong



Are there 3D
representations
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Criterion:
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3D representation explain
performance across multiple
tasks?

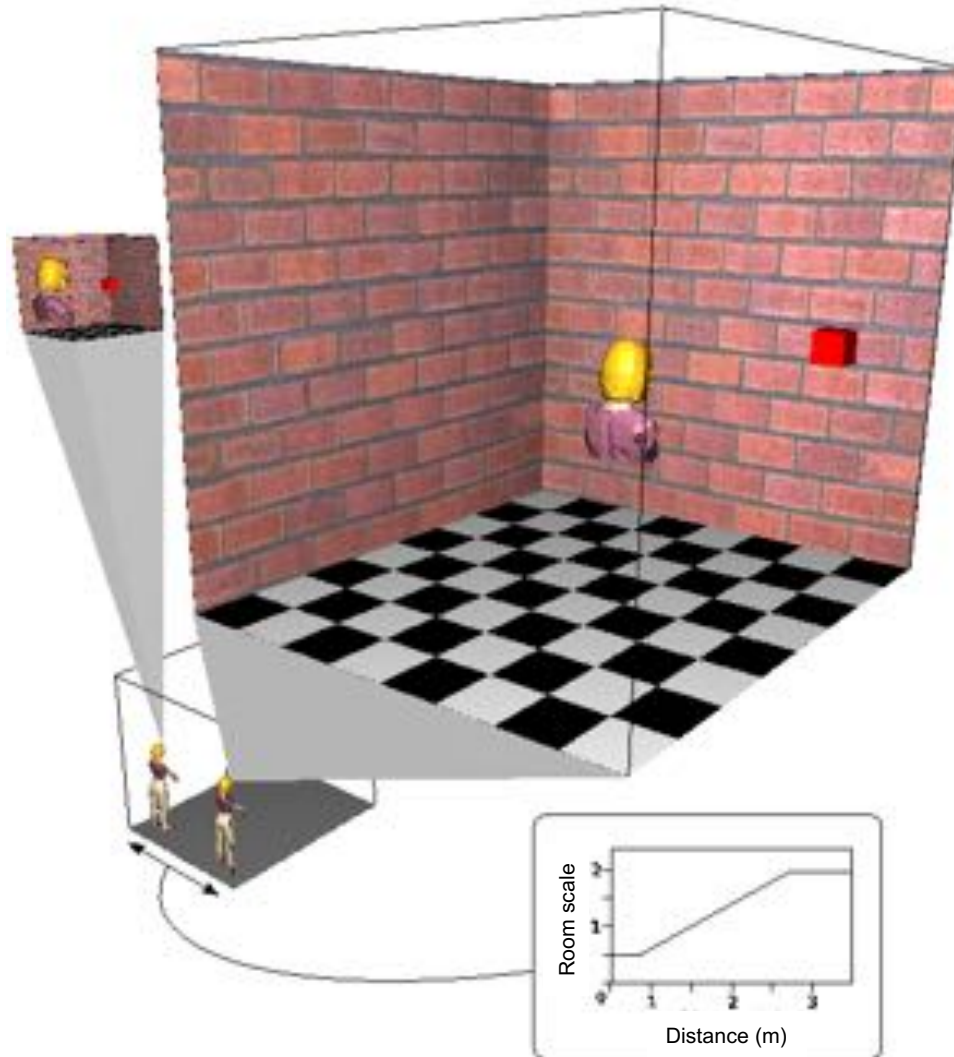
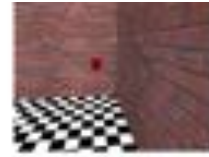
No

Relative depth judgements

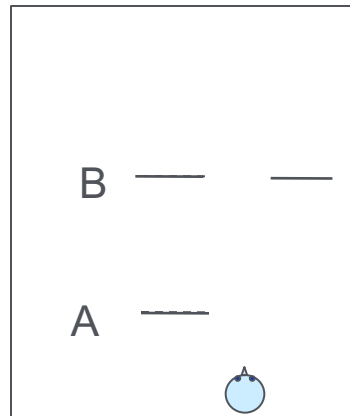
View in
small room



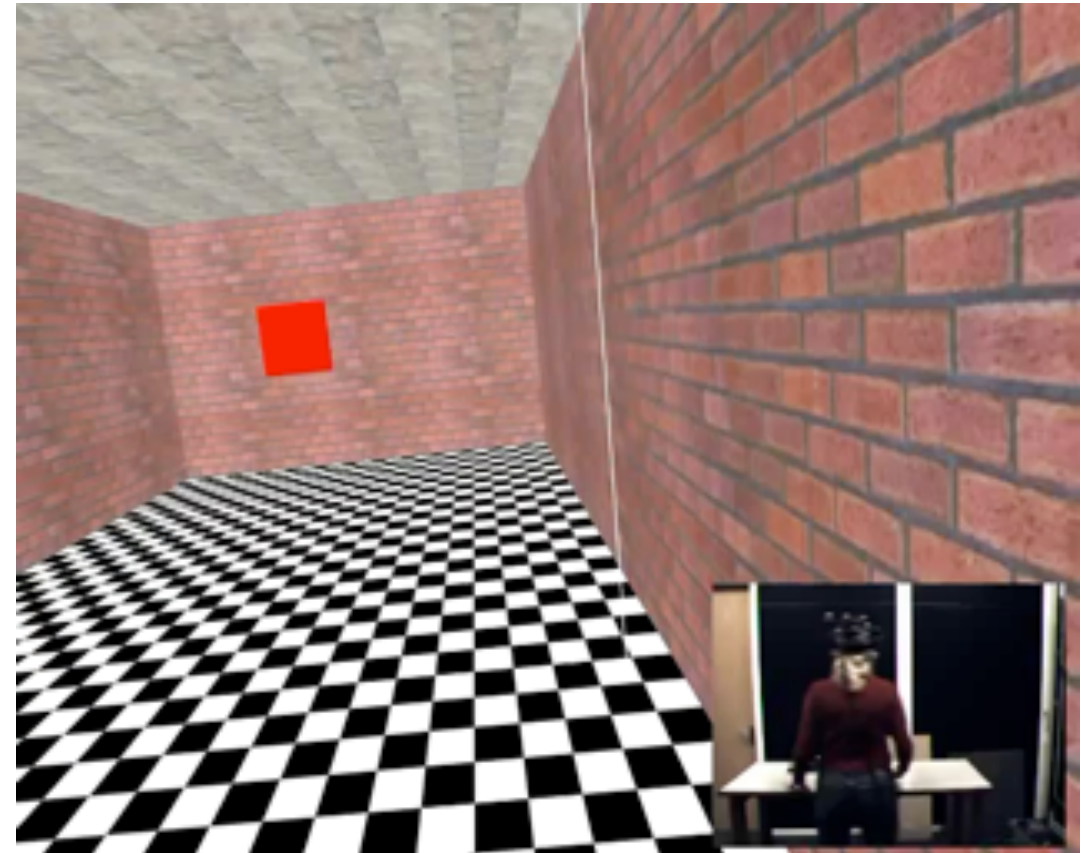
View in
large room



Relative depth judgements



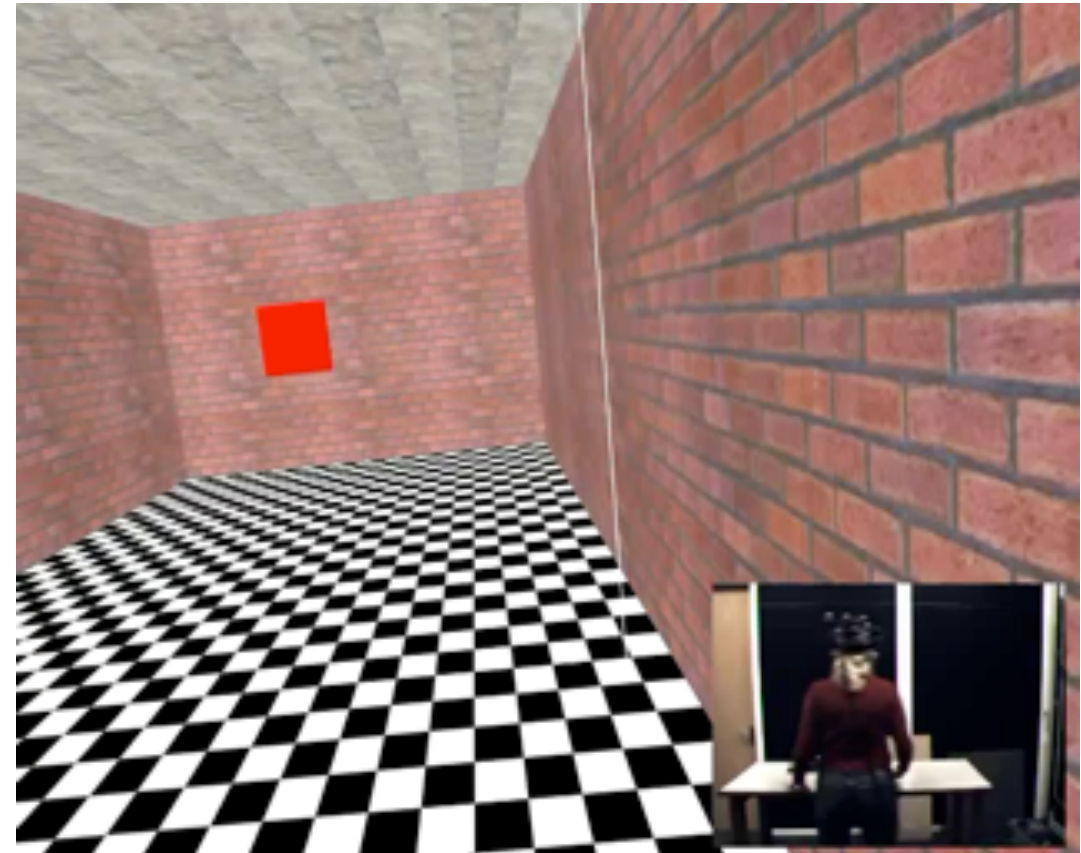
A, B and D are at the same
perceived distance



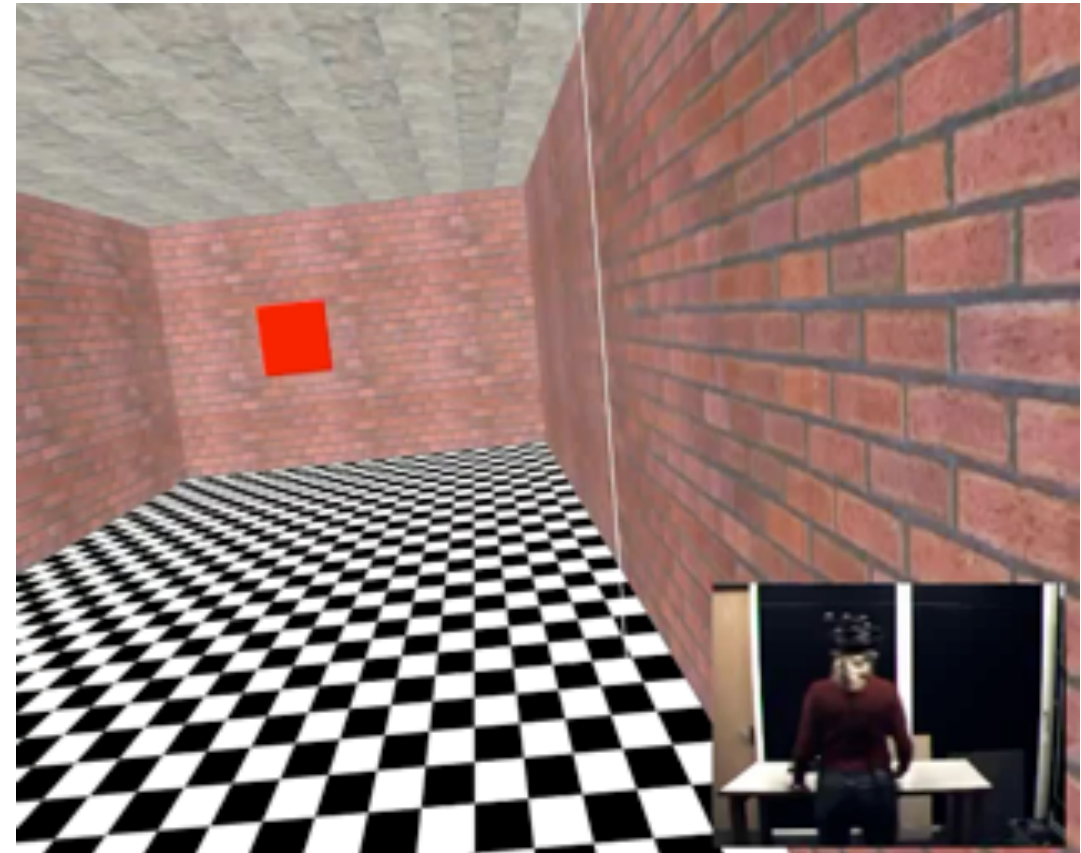
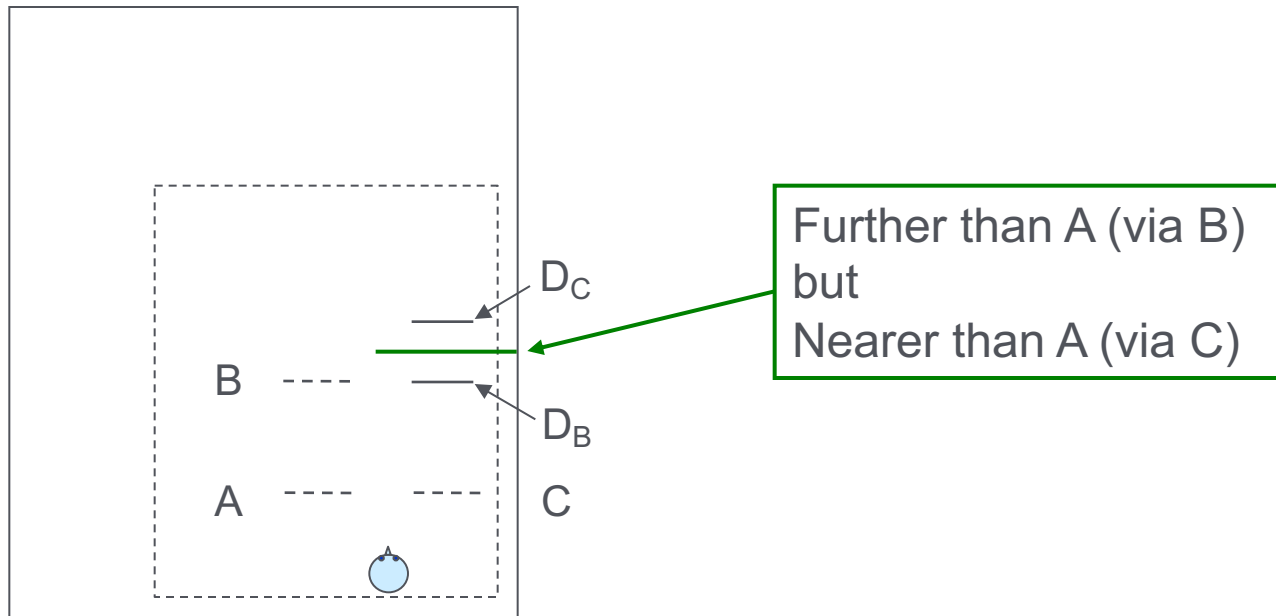
Relative depth judgements



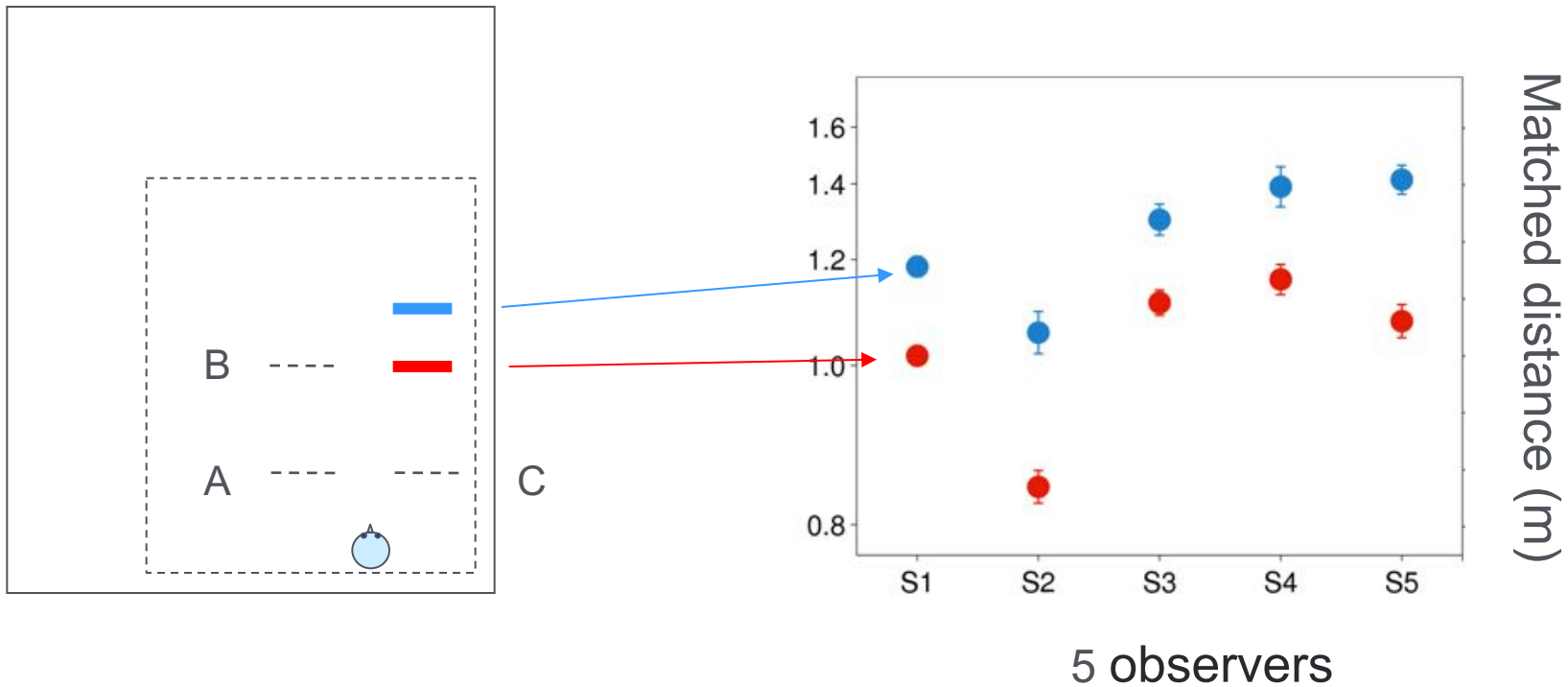
A, C and D are at the same
perceived distance



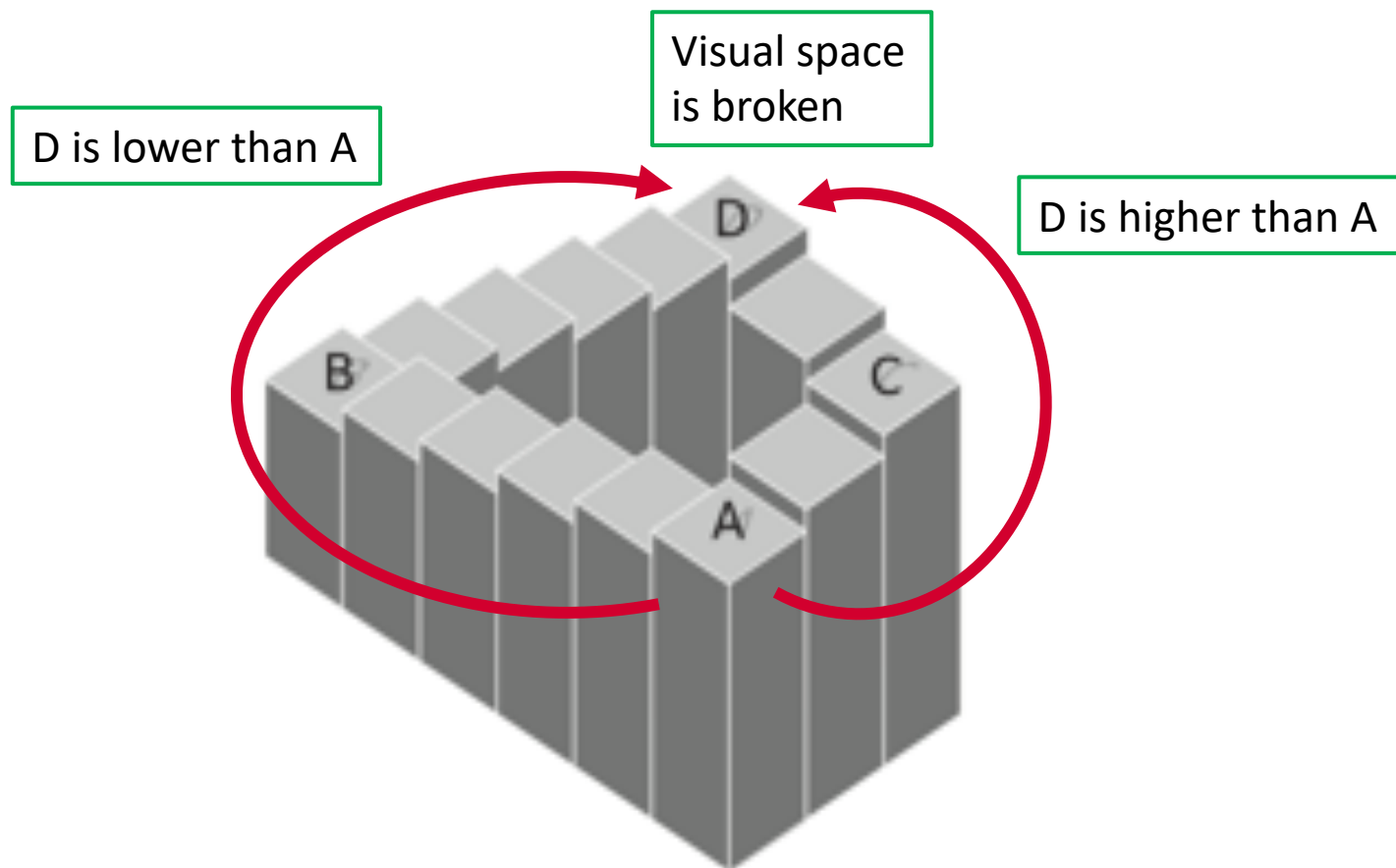
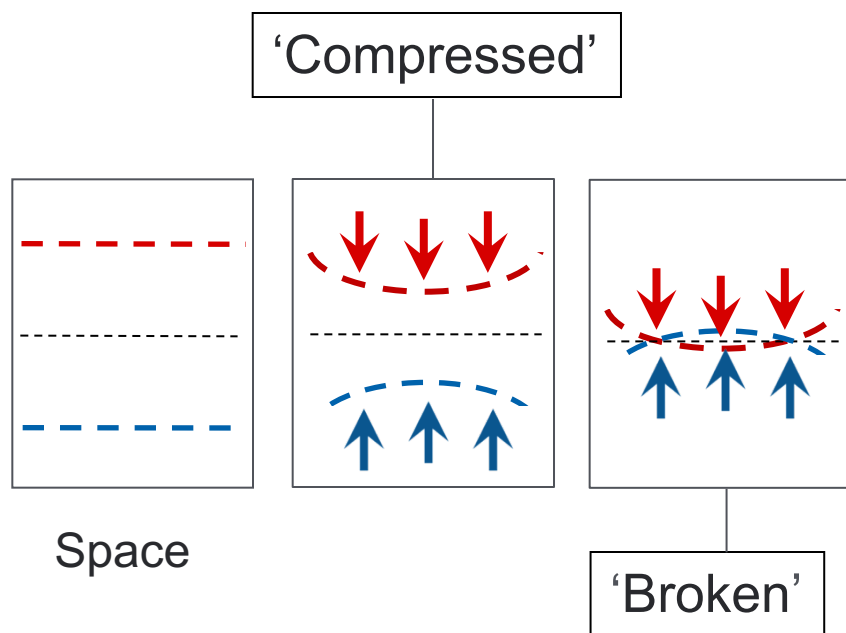
Relative depth judgements



Relative depth judgements



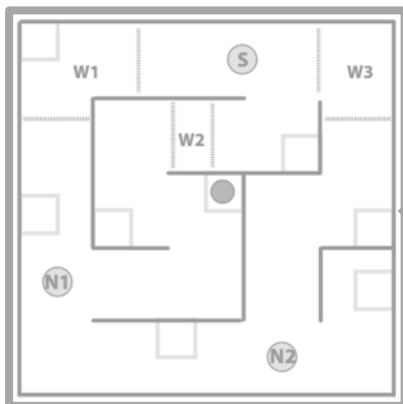
Relative depth judgements



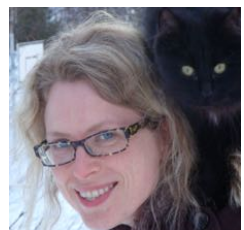
Three experiments:



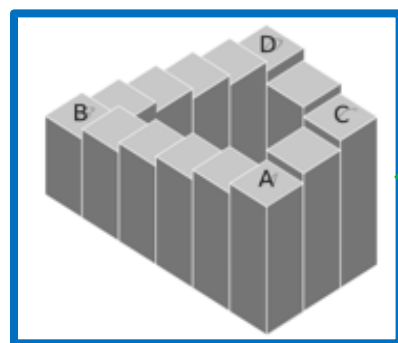
Alex Muryy



Jenny Vuong



Ellen Svarverud



Are there 3D
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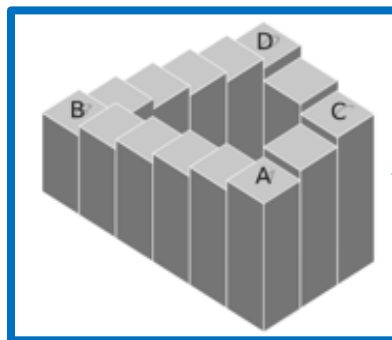
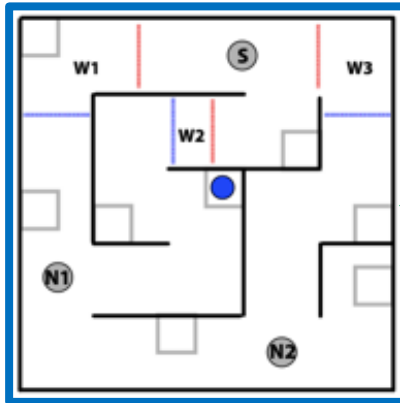
‘Neural rendering’ without a 3D reconstruction

Neural Scene Representation and Rendering

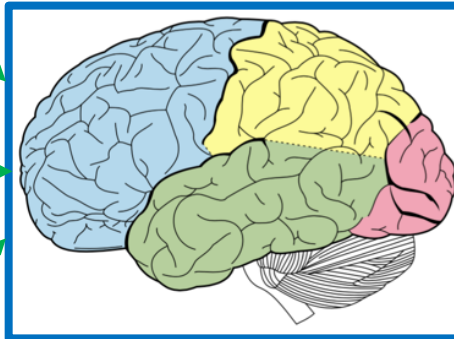
S. M. Ali Eslami*, Danilo J. Rezende*, Frederic Besse, Fabio Viola, Ari S. Morcos, Marta Garnelo, Avraham Ruderman, Andrei A. Rusu, Ivo Danihelka, Karol Gregor, David P. Reichert, Lars Buesing, Theophane Weber, Oriol Vinyals, Dan Rosenbaum, Neil Rabinowitz, Helen King, Chloe Hillier, Matt Botvinick, Daan Wierstra, Koray Kavukcuoglu and Demis Hassabis



Take home message:



Are there 3D
representations
in the brain?



Only possible to test
alternative hypotheses
if the observer moves:
i.e. VR is essential



Thanks...



Alex Muryy



Jenny Vuong



Ellen Svarverud



Peter Scarfe



Lyndsey Pickup



Andrew Fitzgibbon



Stuart Gilson

Microsoft[®]
Research

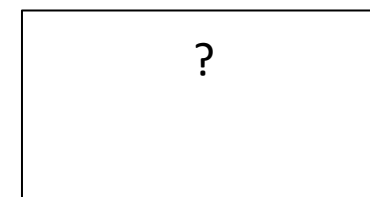
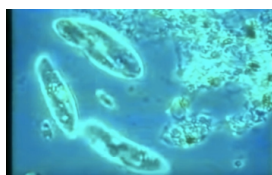
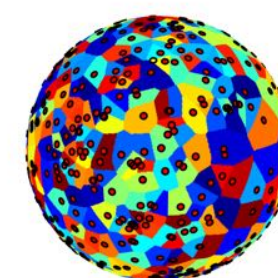
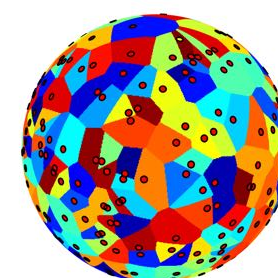
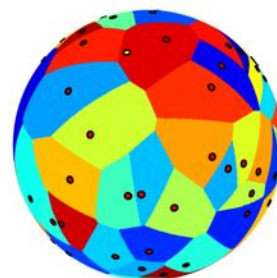
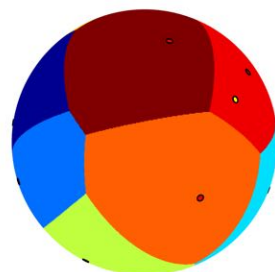
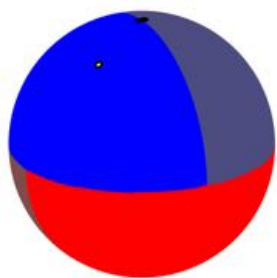
EPSRC

[dstl]

No need for VR....



Evolution of policy networks



- bacterium

- plants

- RL

- humans

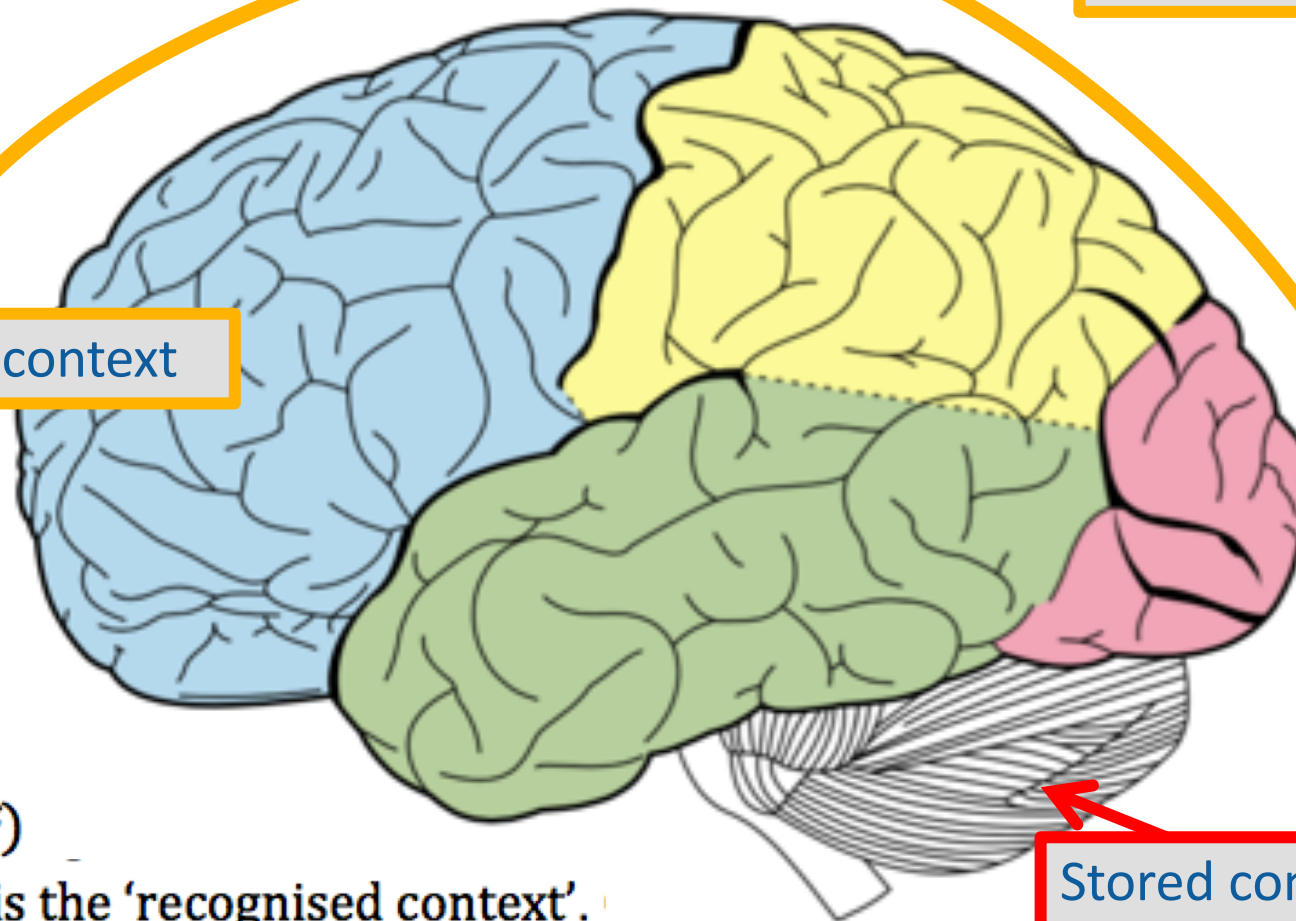
- higher intelligence

A different hypothesis

r

Sensory context

Motivational context



Stored contexts

W

$$k = \operatorname{argmax}_i (W\vec{r})$$

hence $w_{(k,*)}$ is the 'recognised context'.