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Noise performance of microwave humidity sounders over their life time

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Motivation

How does the noise of the MW instruments SSMT2, AMSUB and MHS evolve over their life time?

New aspects in

- **Noise**: Definition and calculation using Allan Deviation
- **MW instruments**: individual instruments of SSMT2, AMSUB, MHS on all platforms
- **Evolution**: assessment over whole life time

→ goals

- overview of usable data
- insight to known issue
- input for uncertainty budget of new FIDUCEO FCDR

Outline

1. Method: Noise definition and calculation
2. Main results
 - a. Noise Evolution and usable data
 - b. Insight to known issue: AMSU-B N16 bias vs other instruments
 - c. Input for uncertainty budget in FCDR
3. Conclusions

1. Method

Noise definition

- “count noise”: Fluctuations in instrumental counts:
 - Deep space view (DSV)
 - View of the internal warm calibration target (IWCT)
- Noise Equivalent Differential Temperature (NEdT)
 - From DSV counts: “cold NEdT”
 - From IWCT counts: “warm NEdT”
 - Rescaling to “scene NEdT”

Noise calculation

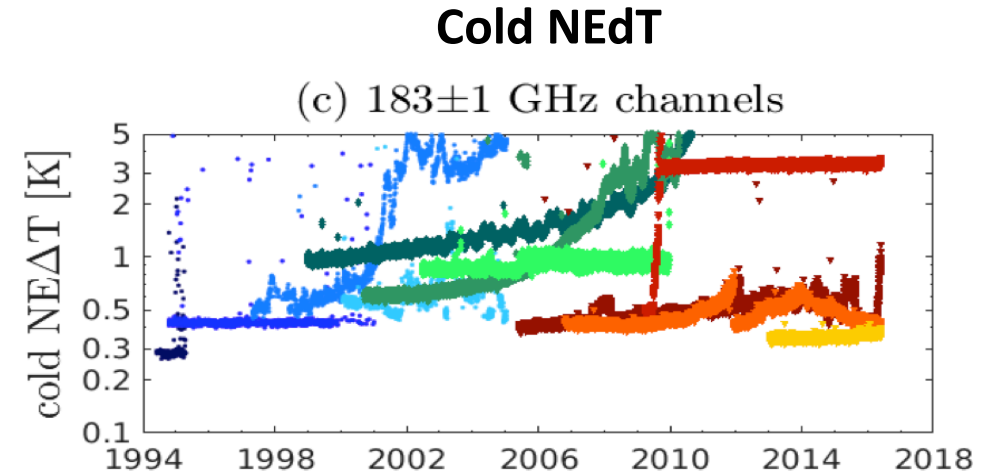
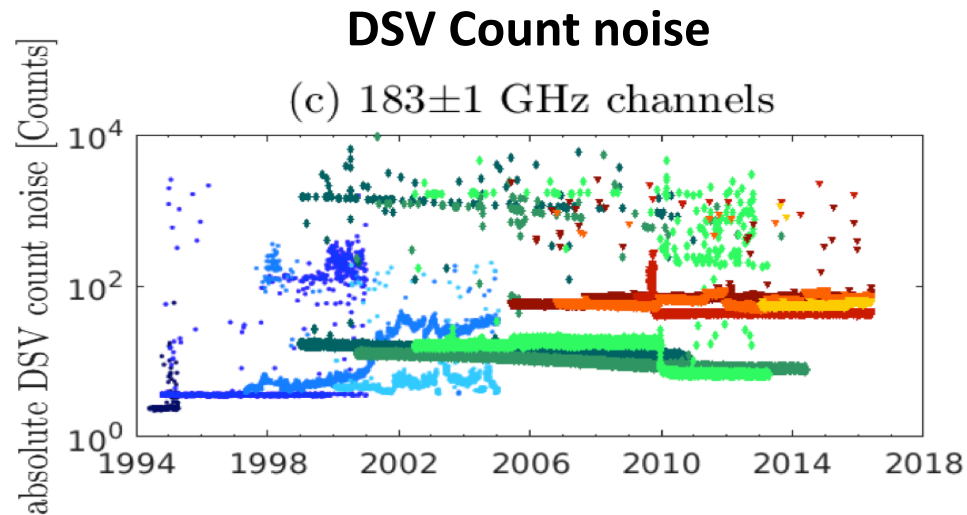
- Allan Deviation: inter-scanline-wise, on each calibration view

$$\Delta C_{\text{DSV}} = \sqrt{\frac{1}{2(N-1)} \sum_{n=1}^{N-1} \sum_{k=1}^K (C_{\text{DSV}_{k,n+1}} - C_{\text{DSV}_{k,n}})^2}$$

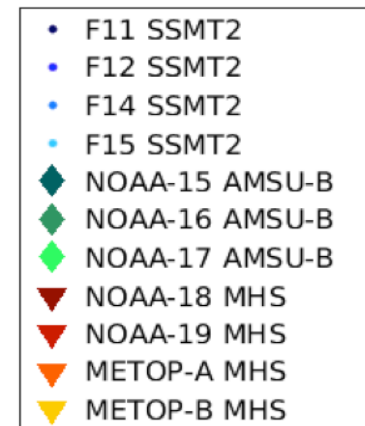
- Advantage: not sensitive to orbital variations
- Scaling of count noise to Temperature NEdT

$$\text{NE}\Delta T_{\text{cold}} = \sqrt{\frac{1}{2(N-1)} \sum_{n=1}^{N-1} \sum_{k=1}^K \left(\frac{C_{\text{DSV}_{k,n+1}} - C_{\text{DSV}_{k,n}}}{G_n} \right)^2}$$

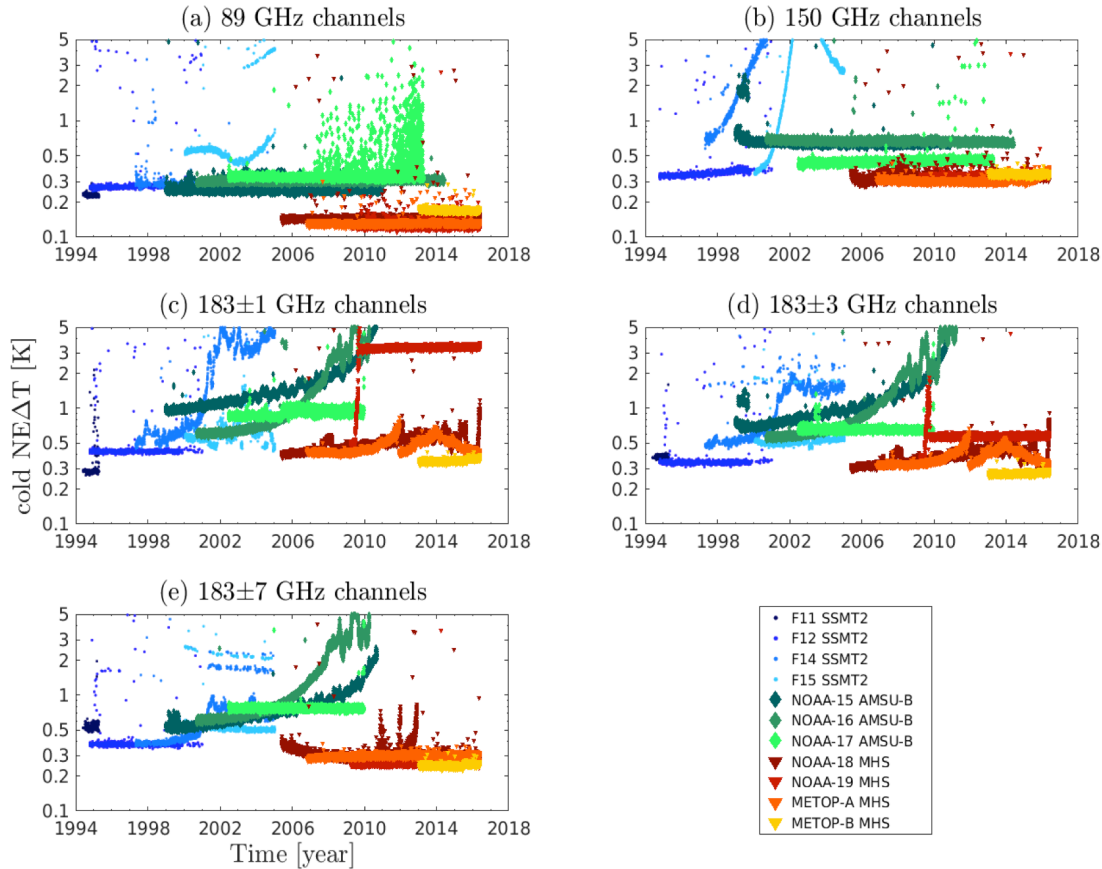
2.a. Noise evolution and usable data



- Behaviour of Count noise and NEdT:
 - Changes in count noise \rightarrow changes in NEdT
 - But: NEdT also reflects changes in gain
- Evolution different for instruments and channels
 - e.g. strong degradation of NOAA15, 16 in Ch3 NEdT
 - on METOP-B: Very stable count noise and NEdT



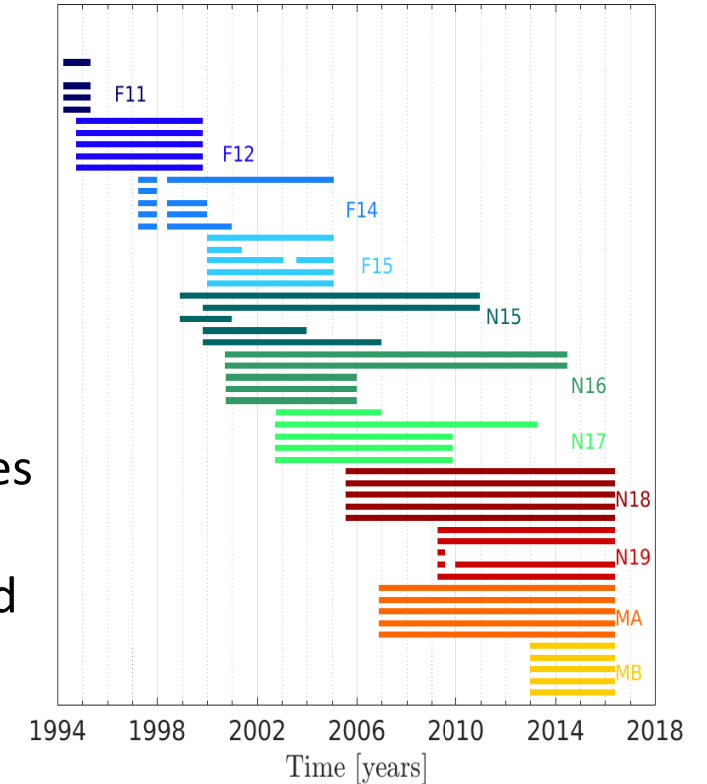
2.a. Noise evolution and usable data



- Usable data:
e.g. NEdT <1K



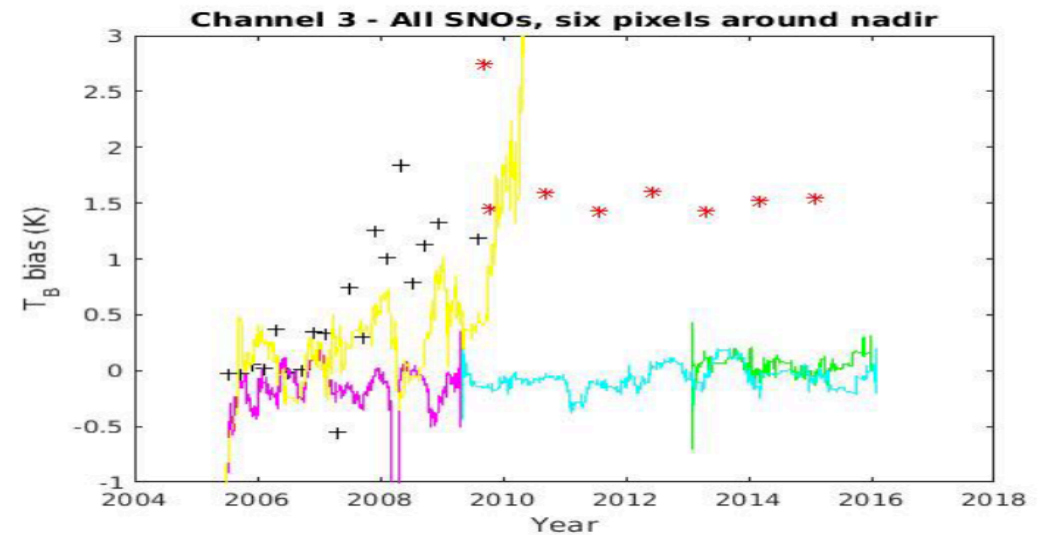
- For NEdT <1K: time series for all channels without gaps may be constructed



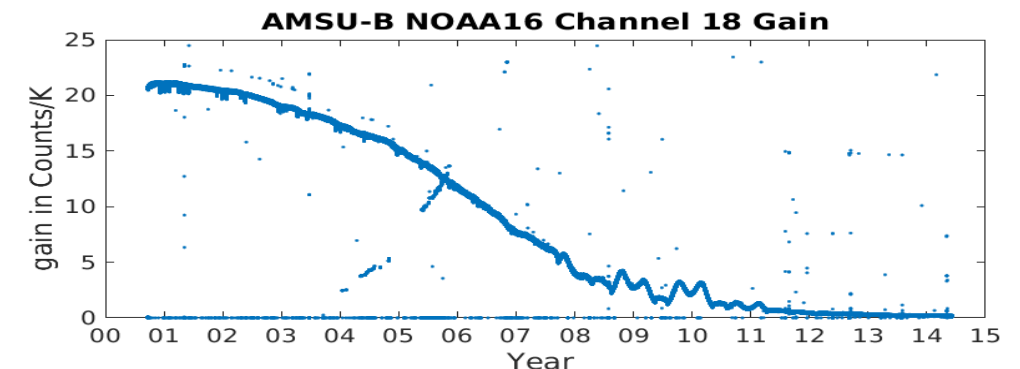
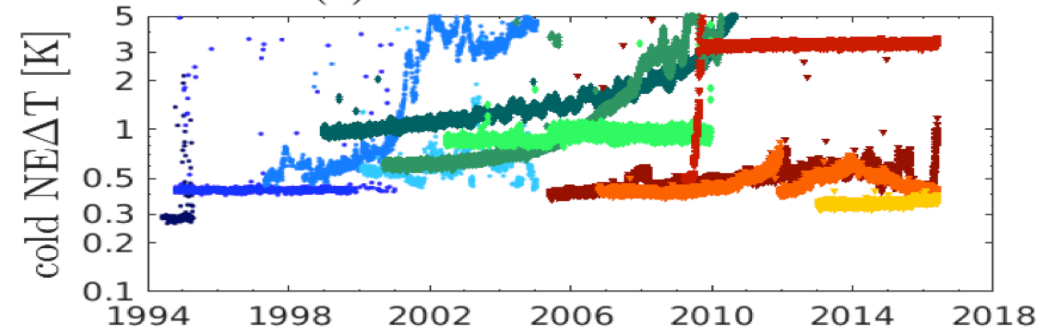
→ “quick look” overview of noise and NEdT for all instruments and channels

2.b. Insight to N16 bias

- Bias N16 vs MHS N18 (yellow) increases dramatically...
- ...so does NEdT (green)
- ...because of the decreasing gain
- RFI has more impact → likely to cause the bias



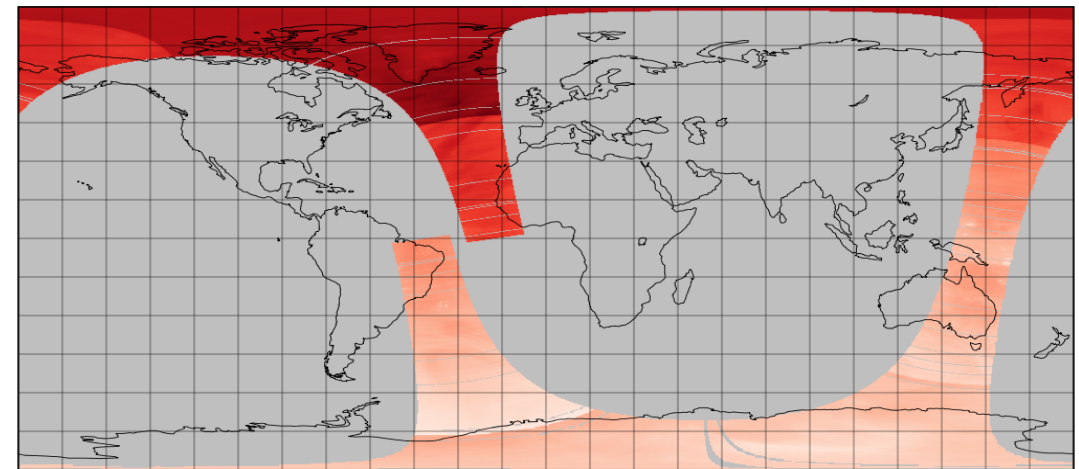
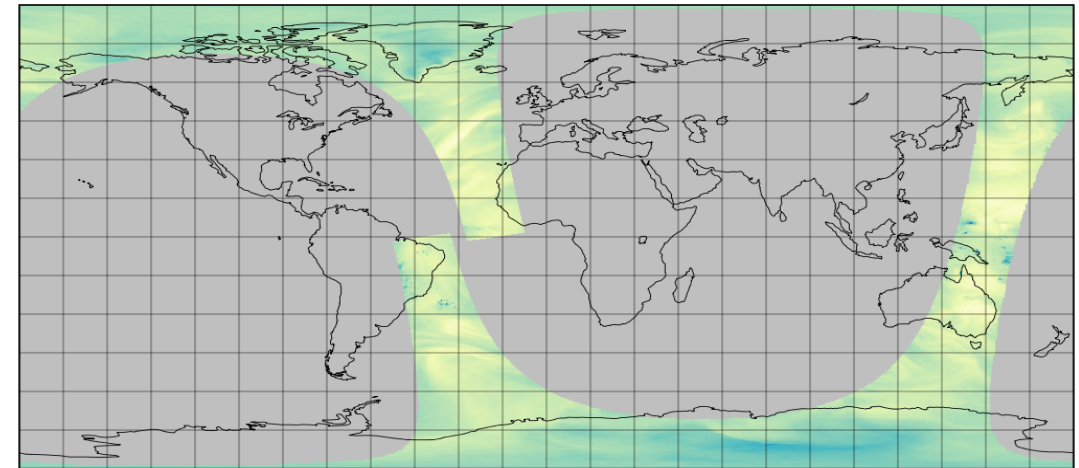
(c) 183 ± 1 GHz channels



2.c. Input for uncertainty budget in FIDUCEO

FCDR

- Count noise estimation (Allan Dev.) applied in FCDR processing
- DSV, IWCT, scene count noise estimated on-the-fly
- Propagated to brightness temperature T_b
→ “uncertainty in T_b due to noise on scene counts” on pixel level



3. Conclusions

- We have used: Allan Deviation (not sensitive to orbital variations) for estimating count noise and NEdT
- We provide: Overview of count noise and NEdT evolution over life time of all individual SSMT2, AMSUB, MHS instruments
- We suggest: RFI as possible explanation for AMSUB N16 bias
- We provide: input for uncertainty budget of FIDUCEO MW FCDR which we work on

Thank you!



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Back up slides

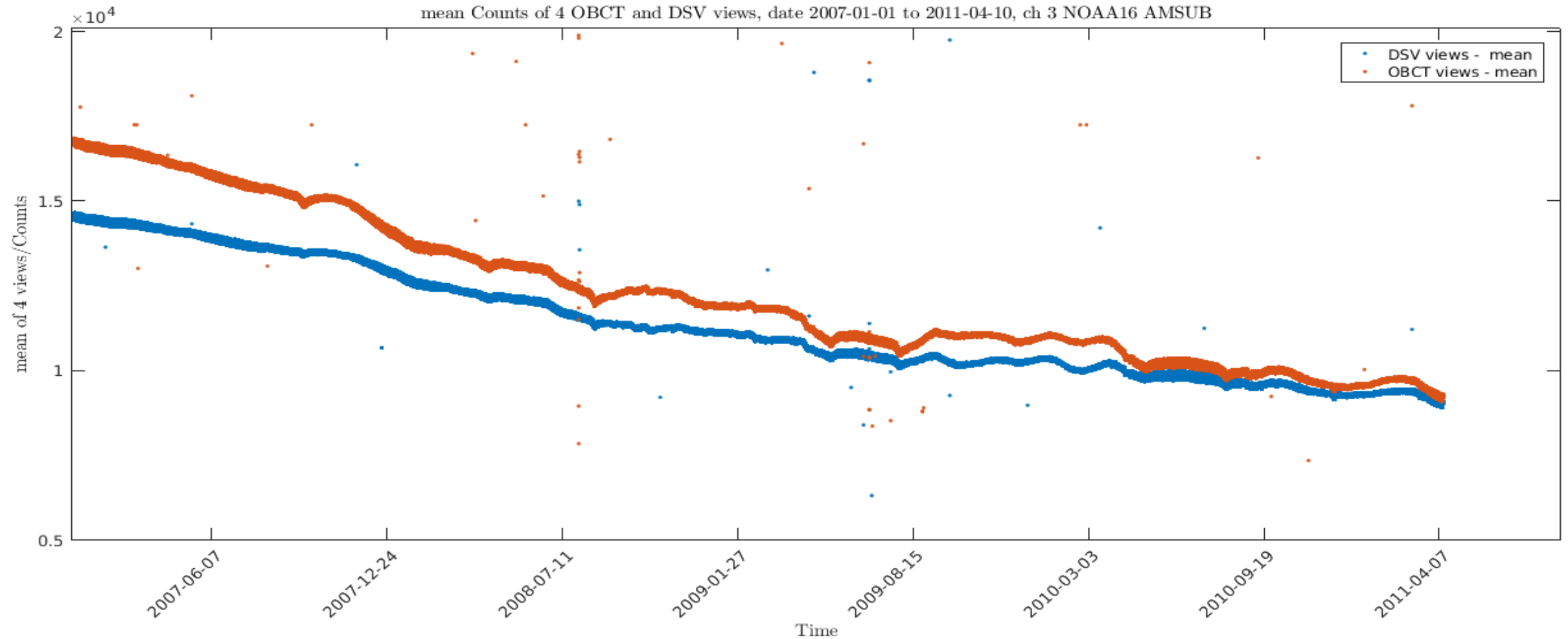
Scene NEdT

- Rescaling for scene NEdT

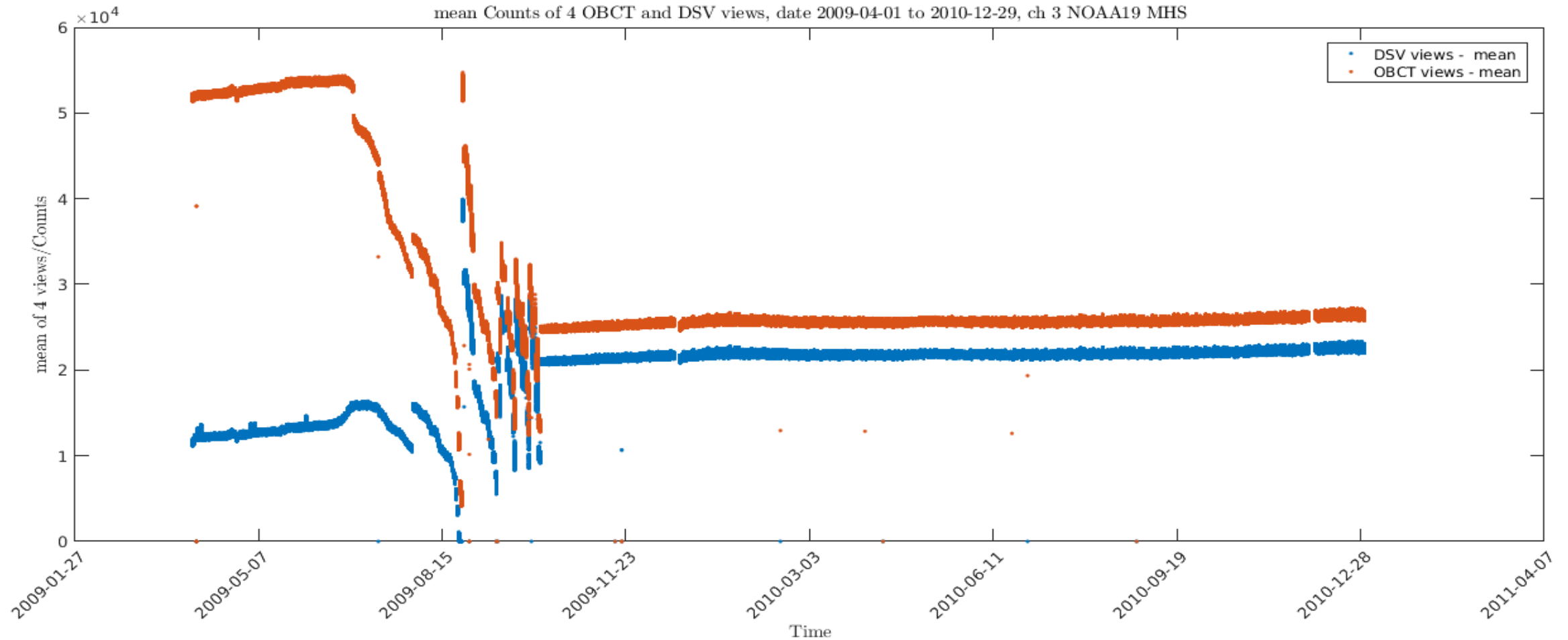
$$\text{NE}\Delta T = \text{NE}\Delta T_{\text{cold}} + (T_{\text{a,scene}} - T_{\text{a,DSV}}) \cdot m$$

$$\text{with } m = \frac{\text{NE}\Delta T_{\text{warm}} - \text{NE}\Delta T_{\text{cold}}}{T_{\text{a,OBCT}} - T_{\text{a,DSV}}}$$

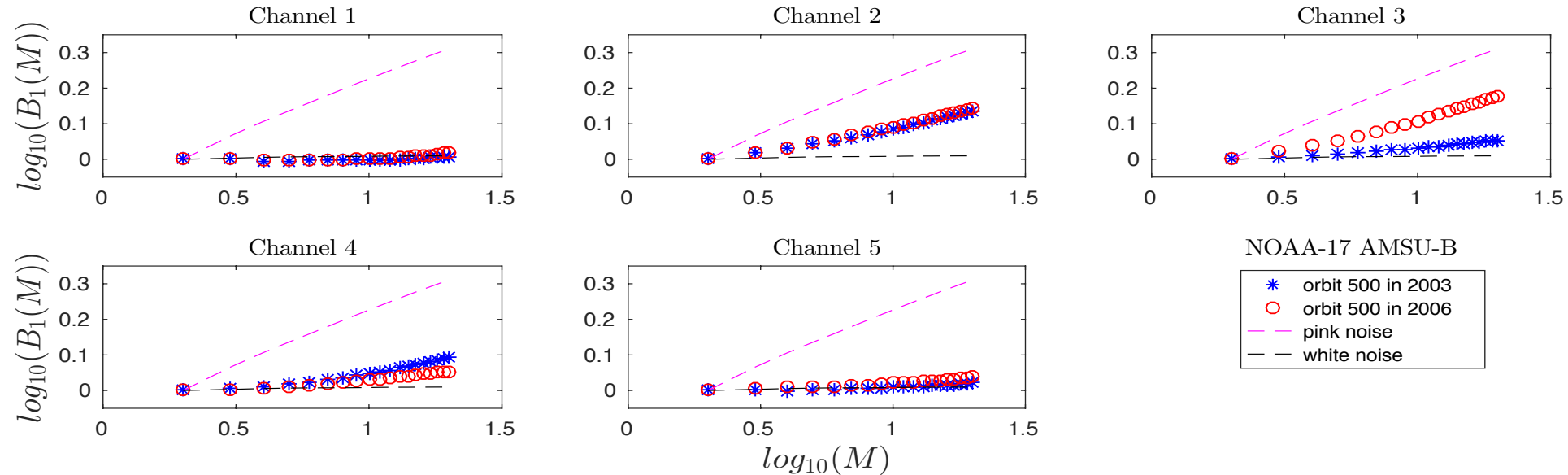
Gain decrease - evolution of counts Channel 3 AMSUB NOAA16



Gain decrease - evolution of counts Channel 3 MHS NOAA19



DSV count noise spectrum



- Noise spectrum calculated with bias function
$$B_1(M) = \frac{\langle \sigma_M^2 \rangle_N}{\langle \sigma_{\text{Allan}}^2 \rangle_N}$$
- Ch2 has pink noise component
- Ch3 has stronger pink noise component in 2006 than in 2003

DSV count noise

- Ch2: inter-pixel-method too low
- Ch3: in 2006, when pink noise stronger, inter-pixel-method too low

